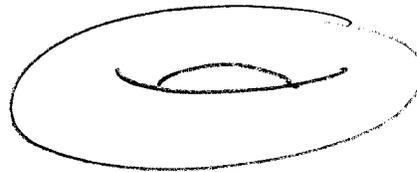


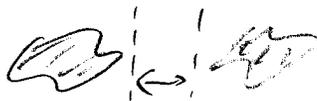
HOMOLOGY & COHOMOLOGY

1. Rough Idea

- Consider the Torus: A ≥ 2 -manifold (can embed in 3D space to display) with two 2D - "holes"



- Want to classify its topology. One fruitful avenue of classification: count "holes" (of various dimensions)



disconnected: "1D-hole"



circle: "2D-hole"



Sphere: "3D-hole" (interior)

etc...

- Powerful method to classify topology & count holes: HOMOTOPY GROUPS $\pi_n(X)$. Classify n -dimensional loops that are deformable into each other eg for torus



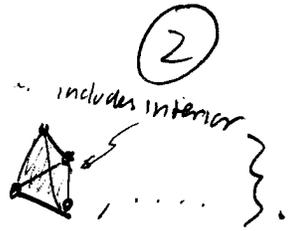
two cycles

$$\pi_1(T) = \mathbb{Z}^2$$

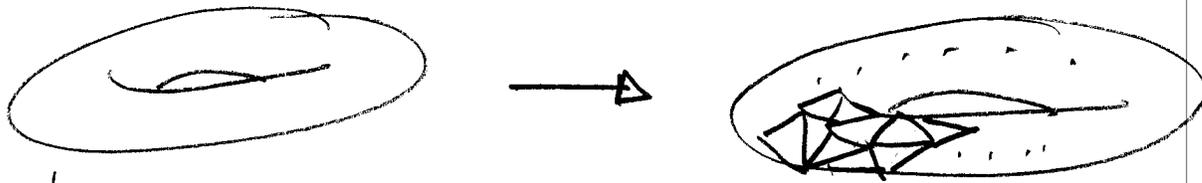
- π_n "detects" $(n+1)$ -dim holes (loops around holes can't be contracted to a pt)
- π_1 is easy to calculate, π_2, π_3, \dots are MUCH HARDER. Could we use something simpler?

• HOMOLOGY

Imagine representing Torus by a polyhedron made up of generalized triangles (simplexes) { •, —, ▲, ... }



(kinda like a 3D computer graphics polygon)

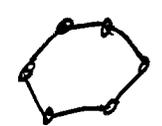


↳ called "Triangulation of Torus". Not unique! (That's OK)

↳ There is a way to algebraically represent all possible p -dim sub-polyhedra of the triangulation. They form the p -chain group C_p

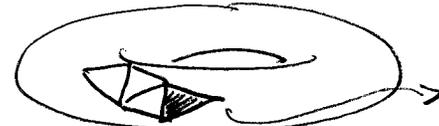


↳ eg 1-D sub polyhedron = "lines connecting vertices of the triangulation"

↳ Can then ask: which ones of these chains have NO BOUNDARY?
eg "—•" has boundary "•",  has no boundary

↳ they form the group $Z_p \subset C_p$

↳ Can furthermore ask: which of these boundary-less chains are themselves just the boundaries of a higher-dim sub-polyhedron of the torus

↳ eg  has boundary , which itself has no boundary

↳ they form the group $B_p \subset Z_p \subset C_p$

↳ Now, the interesting question is: WHICH p-CHAINS ARE BOUNDARY-LESS BUT ARE NOT THEMSELVES BOUNDARIES? → THEY ENCLOSE "HOLES" ☹☹



this cycle encloses one of the "holes" of the torus

Define pth HOMOMOLOGY GROUP

$$H_p \equiv \frac{Z_p}{B_p}$$

free & finitely generated

cyclic "torsion subgroup"

H_p is abelian, and can show $H_p = G \oplus T$

- ↳ rank G counts $(p+1)$ -dim holes' → $H_1(T) = \mathbb{Z}^2$
- ↳ cyclic torsion subgroup contains info on how space is TWISTED!

(Note homology groups have down-index)

- Homology is awesome, but very tedious to calculate.
Also needs "global" information: boundary operator " ∂ "

↳ COHOMOLOGY is dual to homology and much more powerful because its construction only requires local information (" ∂ " \rightarrow exterior derivative), and it also has an additional RING STRUCTURE that allows it to (potentially?) distinguish between two spaces with identical homology groups.

• COHOMOLOGY:

Construction of dual to C_p, Z_p, B_p, H_p :

recall: $w = T_{i_1, \dots, i_p} dx^{i_1} \wedge \dots \wedge dx^{i_p}$ ← antisym rank p tensor

$dw = \frac{\partial T_{i_1, \dots, i_p}}{\partial x^{i_{p+1}}} dx^{i_{p+1}} \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p}$
is a $p+1$ form

C_p = group of p -cycles

↳ roughly speaking, a p -form on our manifold M $w \in \Omega^p(M)$ defines a map $w: C_p \rightarrow \mathbb{R}$ by $(c \in C_p)$

$\langle w, c \rangle \equiv \int_c w$

\Rightarrow Stokes' Thm: boundary op. & ext. derivative are formal ADJOINTS of each other

$\langle dw, c \rangle = \langle w, \partial c \rangle$

$\Rightarrow C^p =$ set of all p -forms (co-chains) on M

(all defined with respect to some manifold M)

$Z^p =$ p -forms satisfying $dw = 0$

space of CLOSED p -forms

$B^p =$ p -forms that can be written as $w = d\eta$

space of EXACT p -forms

(cup-index!)

• De Rham Cohomology groups: set of closed p -forms on M that are NOT exact

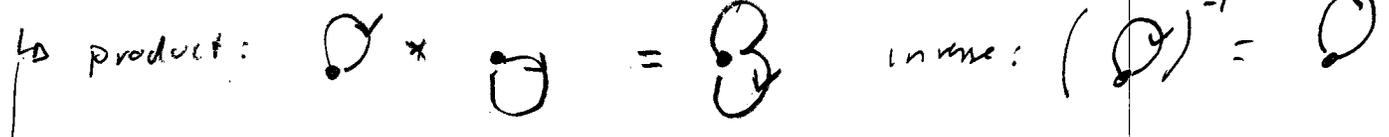
$$H^p = \mathbb{Z}^p / B^p$$

- also counts $(p+1)$ -dim holes
- has additional Ring structure

2. Homotopy Groups

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• 1D loop: map $\alpha: [0,1] \rightarrow \text{topological space } X$ s.t. $\alpha(0) = \alpha(1) = x_0 \in X$



↳ $\pi_1(X, x_0)$ = set of homotopy classes of 1-D loops based on x_0

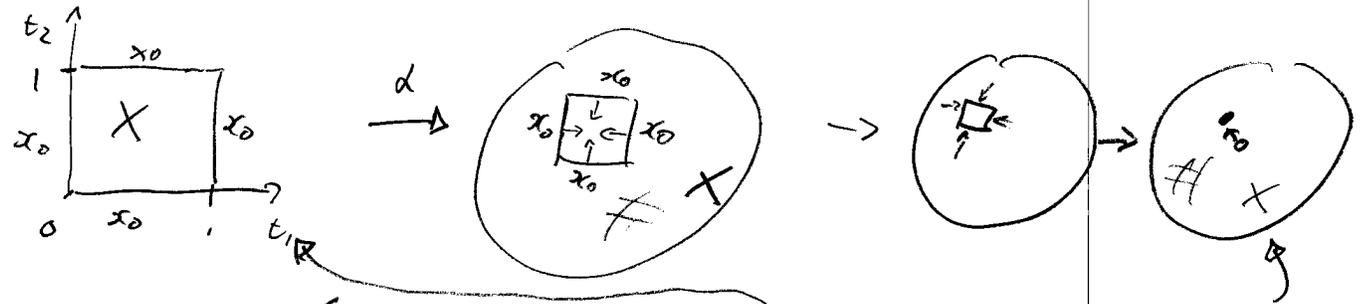
↳ X path connected: $\pi_1(X, x_0) \cong \pi_1(X, x_1) = \pi_1(X)$

↳ There is a "calculating theorem" that gives algorithm for calculating $\pi_1(X)$

• higher-dimensional loops: map $\alpha: I_n \rightarrow X$
s.t. $\partial I_n \rightarrow x_0 \in X$

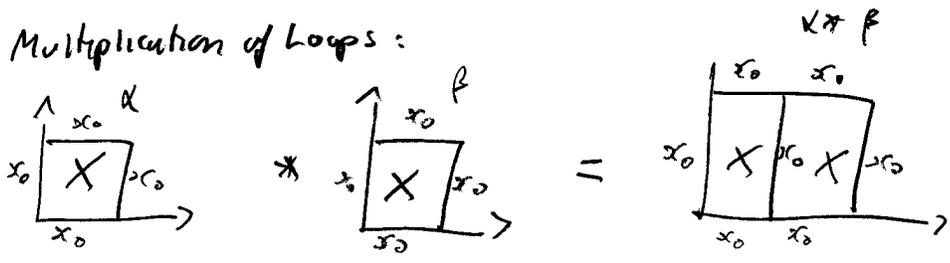
(I_n is closed n-dim cube, of course top. equivalent to S^n but easier to handle)

↳ 2D example good with pictures:



Connection to $S^2 \rightarrow U(1)$ monopole: $\pi_2(S^2)$ is the sphere $S^2 @ \infty$, and this is the field space of the Higgs field. π_2 classifies maps $S^2 \rightarrow M_2$ (vacuum manifold)

↳ Multiplication of Loops:



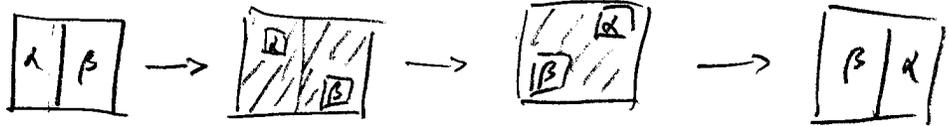
again, particular $x_0 \in X$ does not matter for path-connected X , often omit.

↳ form group of equivalence classes of n-loops: $\pi_n(X, x_0)$

note: $\pi_n(X \otimes Y) = \pi_n(X) \oplus \pi_n(Y)$

↳ $\pi_n, n > 1$, is always abelian: $\alpha \beta = \beta \alpha$

/// = mapped to x_0

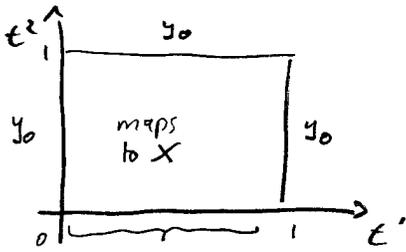


→ = homotopic to

• Relative homology groups : for closed $Y \subset X$, $\alpha: I_n \rightarrow X$

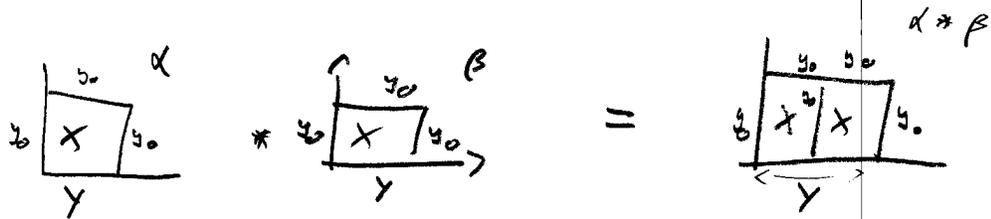
⊗ s.t. all faces of $I_n \rightarrow y_0 \in Y$ except for one open face $J_{n-1} \rightarrow Y$ (ie a path in Y)

eg $n=2$



maps to $Y \rightarrow (n-1)$ -dim path in Y

↳ product:



↳ Define group of equivalent loops that can be deformed into each other while preserving property ⊗ : $\pi_n(X, Y, y_0)$

↳ hence two relative loops with totally inequivalent $(n-1)$ -paths in Y on J_{n-1} are equivalent!!!

• Exact Sequence:

$i_*: \pi_n(Y, y_0) \rightarrow \pi_n(X, y_0)$ is the trivial inclusion map

$j_*: \pi_n(X, y_0) \rightarrow \pi_n(X, Y, y_0)$ is another trivial inclusion map (think of $\pi_n(X, y_0)$ as $\pi_n(X, y_0, y_0)$)

$\partial_*: \pi_n(X, Y, y_0) \rightarrow \pi_{n-1}(Y, y_0)$ is the boundary homomorphism that takes a relative loop $\alpha: I_n \rightarrow X$ and keeps only the $(n-1)$ -dim loop in Y that corresponds to the exceptional face J_{n-1}

⇒ EXACT SEQUENCE ... $\rightarrow \pi_n(Y, y_0) \xrightarrow{i_*} \pi_n(X, y_0) \xrightarrow{j_*} \pi_n(X, Y, y_0) \xrightarrow{\partial_*} \pi_{n-1}(Y, y_0) \xrightarrow{i_*} \dots$

ie image of one map = kernel of the next

↳ USEFUL, eg " $\{0\} \rightarrow A \rightarrow B \rightarrow \{0\}$ " ⇒ " $A \cong B$ "

3. Simplexes

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- m-simplex σ^m = generalized triangle in n -D $\sigma^0 = \bullet$ $\sigma^2 = \triangle$
 $\sigma^1 = \text{---}$ $\sigma^3 = \text{tetrahedron}$

$\hookrightarrow \sigma^m = \left\{ x = \sum_{i=1}^{m+1} \lambda_i x_i \mid \lambda_i \geq 0, \sum \lambda_i = 1, x_i \text{ are linearly independent} \right\}$

$\hookrightarrow \forall x \in \sigma^m$ has barycentric coords $\{\lambda_i\}$, x is the center of mass of σ^m with masses λ_i placed on points x_i .

\hookrightarrow often write $\sigma^m = [x_1, x_2, \dots, x_{m+1}]$

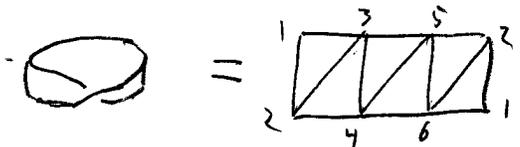
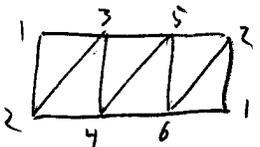
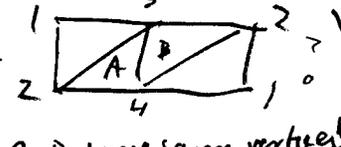
$\hookrightarrow j^{\text{th}}$ face of $\sigma^m = [x_1, \dots, \overset{\wedge}{x_j}, \dots, x_{m+1}]$ $\wedge =$ "omitted"
 $= \{ \lambda_i x_i \mid \lambda_j = 0 \}$

- A simplicial complex K is a finite collection of distinct simplexes in some \mathbb{R}^n s.t.
 - 1) $\forall \sigma^r \in K \rightarrow$ all faces $\in K$
 - 2) $\sigma^p, \sigma^q \in K \rightarrow \sigma^p \cap \sigma^q = \emptyset$ or common face of σ^p, σ^q

\hookrightarrow i.e. simplexes that "fit together nicely"

$\hookrightarrow |K| = \cup \{K\}$ is the polyhedron constructed out of simplex K .

- Triangulation of space X = polyhedron $|K|$ that is homeomorphic to X , not unique.

\hookrightarrow eg Moebius strip  =  (why not )
 (Simplexes A, B have same vertices!)

= $\{123\} + \{234\} + \{345\} + \{456\} + \{256\} + \{126\} + \text{faces}$

oriented p-simplex

obtained from p -simplex $\sigma^p = [v_0, \dots, v_p]$ and choosing an ordering of vertices v_i .

Then $\pm \sigma_p =$ equivalence class of odd permutations of given ordering. $[v_2, v_1] = -[v_1, v_2]$

- Boundary Operator for oriented simplex $\sigma^p = [v_0, \dots, v_p]$: $\partial \sigma^p = \sum_{j=0}^p (-1)^j [v_0, \dots, \overset{\wedge}{v_j}, \dots, v_p]$
- This satisfies $\partial^2 = 0$.
- 1) $\sigma = [12] = \text{---}$ $\rightarrow \partial \sigma = [2] - [1] = 0$
 - Example: 2) $\sigma = [12] + [23] = \text{---}$ $\rightarrow \partial \sigma = [2] - [1] + [3] - [2] = [3] - [1]$
 - 3) $\sigma = [123] = \text{triangle}$ $\rightarrow \partial \sigma = [23] - [13] + [12]$ $\rightarrow \partial^2 \sigma = [3] - [2] - [3] + [1] + [2] - [1] = 0 \checkmark$

4. Homology

(9)

• (Assume for now top space X is triangulable.) $H_p(X)$ is a topological invariant we will calculate using a triangulation K of X .

• For a given triangulation K of topological space X with $\dim n$.

↳ $C_p(K) =$ free abelian group generated by the oriented p -simplexes of K
 $= \{ C_p \mid C_p = \sum_{i=1}^{r_p} f_i \sigma_i, f_i \in \mathbb{Z}, r_p = \# \text{ } p\text{-simplexes in } K \}$
 $=$ " p -chain group of K "

↳ addition: $\sum f_i \sigma_i + \sum g_i \sigma_i = \sum (g_i + f_i) \sigma_i$

↳ $\text{nil } C_p(K) = \{0\}$ for $p > n$

↳ boundary operator acts linearly on $C_p \in C_p(K)$

↳ $Z_p(K) = \ker \partial_p \subset C_p =$ p -chains $C_p \in C_p$ satisfying $\partial C_p = 0$
 $=$ " p -dim cycle group"

↳ $B_p(K) =$ p -cycles for which $\exists C_{p+1} \in C_{p+1}$ s.t. $\partial C_{p+1} = b_p \in B_p(K)$
 $=$ " p -dim boundary group" $= \text{Im } \partial_{p+1}$

• $C_p(K) \subset Z_p(K) \subset B_p(K)$. $\implies H_p(K) \cong \frac{Z_p(K)}{B_p(K)} = p^{\text{th}}$ homology group
 $\begin{matrix} \uparrow & \uparrow & \uparrow \\ p\text{-chain} & p\text{-cycles} & p\text{-boundaries} \end{matrix}$

ie $H_p =$ group of p -cycles that are not trivially cycles, ie are just boundaries.

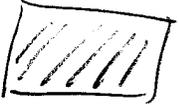
• H_p is independent of triangulation, even though Z_p, B_p, C_p are not.

• Thm: $\forall K$ is contractible to a pt, $H_p(K) = \begin{cases} \{0\} & p \neq 0 \\ \mathbb{Z} & p = 0 \end{cases}$

• $H_p \cong \frac{Z_p}{B_p} \cong C_p + T_p$ $C_p =$ abelian, uniquely generated by finite # generators. # generators = p^{th} Betti Number
 $= \# (p+1)\text{-dim Holes in } K!$

$T_p =$ cyclic torsion subgroup. Contains twist info.

Example 1

Homology groups of  $\rightarrow K = \triangle_{012} = \{[012] + \text{faces}\}$

Chain groups:

$$C_0(K) = \{a_0[0] + b_0[1] + c_0[2]\} \cong \mathbb{Z}^3$$

$$C_1(K) = \{a_1[12] + b_1[02] + c_1[01]\} \cong \mathbb{Z}^3$$

$$C_2(K) = \{a_2[012]\} \cong \mathbb{Z}$$

$$C_{3+}(K) = \{0\}$$

Cycle groups:

- $\forall c_0 \in C_0(K), \partial c_0 = 0 \rightarrow Z_0(K) = C_0(K) \cong \mathbb{Z}^3$
- if $z = a_1[12] + b_1[02] + c_1[01] \in C_1(K), \partial z = 0 = (-a_1 - b_1)[0] + (a_1 - c_1)[1] + (b_1 + c_1)[2]$
 $\rightarrow a_1 = -b_1 = c_1 \Rightarrow Z_1(K) = \{a([12] - [02] + [01])\} \cong \mathbb{Z}$ (gen $\times \Delta$)
- if $c \in C_2(K), \partial c \neq 0 \Rightarrow Z_2(K) = \{0\}$

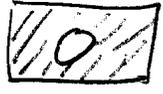
Boundary groups:

- $B_0(K) = \partial C_1(K) = \{(-a_1 - b_1)[0] + (a_1 - c_1)[1] + (b_1 + c_1)[2]\} \cong \mathbb{Z}$ since the coeffs add to zero
- $B_1(K) = \partial C_2(K) = \{a_2([12] - [02] + [01])\} = Z_1(K) \cong \mathbb{Z}$
- $B_2(K) = \partial C_3(K) = \{0\}$

Homology groups:

$$H_0(K) = \frac{Z_0(K)}{B_0(K)} \cong \frac{\mathbb{Z}^3}{\mathbb{Z}} = \mathbb{Z}; \quad H_1(K) = \frac{Z_1(K)}{B_1(K)} = \frac{\mathbb{Z}}{\mathbb{Z}} = \{0\}; \quad H_2(K) = \frac{Z_2(K)}{B_2(K)} = \frac{\{0\}}{\{0\}} = \{0\}$$

Example 2

Homology group of  $\rightarrow K' = \triangle_{012} = \{[01] + [12] + [02] + \text{faces}\}$

- $H_0(K') = H_0(K) = \mathbb{Z}$ since 1,2 simplex structure of K, K' the same
- $H_1(K')$: $C_1(K) = C_1(K') = \mathbb{Z}^3; \quad Z_1(K') = Z_1(K) = \mathbb{Z}$
 BUT $C_2(K') = 0 \rightarrow B_1(K') = \{0\}$
 $\Rightarrow H_1(K') = \frac{Z_1(K')}{B_1(K')} = \mathbb{Z}$: detects hole!!

Remarks

(11)

- Similar to homotopy groups, can define relative homology groups which also define an exact sequence. For $K \supset L$,

$$\dots \xrightarrow{\partial_*} H_p(L) \xrightarrow{i_*} H_p(K) \xrightarrow{j_*} H_p(K; L) \xrightarrow{\partial_*} H_{p-1}(L) \xrightarrow{i_*} \dots$$

This is actually **MORE POWERFUL** for homotopy groups,

since there is eg an excision thm whereby $H_p(K, L) = H_p(K - L_0, L - L_0)$

where $L_0 \subset \text{interior of } L$. THIS ALLOWS FOR RELATIVELY EASY CALCULATION OF $H_p(X)$ FOR MANY CASES.

↳ even so, can always calculate H_p by "brute force".

→ H_p contains a little less info than π_p , but we can always (?) calculate it!!!

$$\bullet H_p(X \times Y, \mathbb{Q}) = \bigoplus_{p=k+q} (H_k(X, \mathbb{Q}) \otimes H_q(Y, \mathbb{Q}))$$

\mathbb{Q} means we take \mathbb{C} coeffs to be rational instead of \mathbb{Z} . this removes torsion subgroup of H_p .

$$\bullet H_p \text{ gives us Euler characteristic: } \chi(K) = \sum_{p=0}^n (-1)^p l_p = \sum_{p=0}^n (-1)^p \text{rank}(G_p)$$

\uparrow
p -simplexes

Generalizing this to arbitrary topological space X

- Consider top. space X (not necessarily triangulable).
(This will also be more suited to discussion of COHOMOLOGY!)

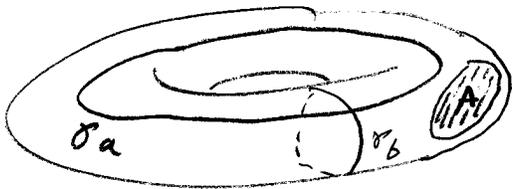
- Define "standard simplex" Δ_p : literally just representative abstract examples of p -simplexes, used to define the topology of a p -dim path

$\Delta_0 = \bullet$ $\Delta_1 = \text{---}$ $\Delta_2 = \text{triangle}$ (includes interior) etc

← regard these (?) as actual manifolds in their own right!

- Define singular p -chain λ_i^p in X as maps $\lambda_i^p: \Delta_p \rightarrow X$

e.g. $X = \text{Torus}$



$\lambda_a^1: \Delta_1 \rightarrow X$ maps --- to σ_a

$\lambda_A^2: \Delta_2 \rightarrow X$ maps triangle to patch

\hookrightarrow on torus surface.

↳ Define singular p -chain group $S_p(X) = \{ \sum \lambda_i^p g_i \mid g_i \in \text{abelian } G \}$
(same as (p))

- Define boundary map: $\partial \lambda^p = \sum_{r=0}^p (-1)^r \lambda^p \circ F^r$
 r^{th} face of Δ^p

If $\lambda_A: \Delta_2 \rightarrow X$ takes triangle to patch
 $\lambda_A \circ F^1: \Delta_1 \rightarrow X$ takes --- to loop
 $\lambda_A \circ F^2: \Delta_1 \rightarrow X$ takes --- to loop
 etc

Formal Def'n:
 F^r embeds Δ_{p-1} in Δ_p
 s.t. it maps to r^{th} face of $\Delta_p \Rightarrow F^r: \Delta_{p-1} \rightarrow \Delta_p$
 $\lambda^p \circ F^r: \Delta_{p-1} \rightarrow X$
 is just λ^p restricted to the r^{th} face of Δ_p

- Define singular homology for arbitrary top space X as

$$H_p(X, G) = \frac{\text{Ker}[\partial: S_p \rightarrow S_{p-1}]}{\text{Im}[\partial: S_{p+1} \rightarrow S_p]}$$

5. Cohomology

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Preliminary Remarks:

↳ we introduced homology group $H_p(X, G)$. Previously we used $G = \mathbb{Z}$. Now let $G = \mathbb{R}$

↳ Let X be a differentiable manifold M . Require $\iota_p: \Delta_p \rightarrow M$ to be C^∞ . The group of C^∞ p -chains is $C_p(M)$.

↳ Recall differential forms: $\omega = T_{i_1 \dots i_p} dx^{i_1} \wedge \dots \wedge dx^{i_p} \in \Omega^p(M)$

exterior derivative $d\omega = \frac{\partial T_{i_1 \dots i_p}}{\partial x^{i_{p+1}}} dx^{i_{p+1}} \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p} \in \Omega^{p+1}(M)$

Stokes' Thm $\int_M d\omega = \int_{\partial M} \omega$

↳ $d^2 = 0$

pullback/pushforward: given a map $\phi: M \rightarrow N$,

vectors can be pushed forward $\phi_*: T_p M \rightarrow T_p N$
 $(\phi_* X) f = X f(\phi(p))$

forms can be pulled back $\phi^*: T_p^* N \rightarrow T_p^* M$
 $\langle \phi^* \omega, X \rangle = \langle \omega, \phi_* X \rangle$

closed form: $d\omega = 0$

exact form: $\exists \eta$ s.t. $\omega = d\eta$

• There is a duality between homology & cohomology, but coh. is more powerful (ring structure) and easier to use (local info)

↳ Don't even need homology to construct cohomology groups!

• Integrate over a p-chain: for $c = \sum a_i \lambda_i \in C_p(M)$, $\omega \in \mathcal{E}^p(M)$,

define $\int_c \omega = \sum a_i \int_{\Delta_p} \lambda_i^* \omega$ \leftarrow λ_i^* -form on Δ_p
pullback

\Rightarrow Denote $C^p(M) =$ set of all p-forms (co-chains) on $M = \mathcal{E}^p(M)$

Then $\omega \in C^p$ defines a map $\omega: C_p \rightarrow \mathbb{R}$
 $\langle \omega, c \rangle = \int_c \omega$

\hookrightarrow boundary operator adjoint to ext. derivative by Stokes Thm

$$\langle d\omega, c \rangle = \langle \omega, \partial c \rangle$$

Homology

$C_p(M) =$ set of all C^∞ p-chains on M

$Z_p(M) = \ker \partial_p =$ p-cycles

$B_p(M) = \text{Im } \partial_{p+1} =$ p-boundaries

$H_p(M, \mathbb{R}) = \frac{Z_p}{B_p} =$ pth homology group with real coeffs

Cohomology

$C^p(M) = \mathcal{E}^p(M)$

$Z^p(M) = \ker d_{p+1} =$ closed forms

$B^p(M) = \text{Im } d_p =$ exact forms

$H^p(M, \mathbb{R}) = \frac{Z^p}{B^p} =$ pth deRham cohomology group with real coeffs.

• Duality theorem: $([w], [c]) = \langle w, c \rangle$ for $[w] \in H^p, [c] \in H_p$.

$\dim H^p(M, \mathbb{R}) = \#$ of $(p+1)$ -dim holes in M

• Spheres: $H^p(S^n, \mathbb{R}) = \begin{cases} \mathbb{R} & p=0, n \\ \{0\} & \text{else} \end{cases}$ Tori: $H^p(T^n, \mathbb{R}) = \mathbb{R}^d$ with $d = \binom{n}{p}$

• Define $H^*(M, \mathbb{R}) = \bigoplus H^p(M, \mathbb{R})$. for $[w] \in H^p, [v] \in H^q$, the CUP PRODUCT $[w] \cup [v] = [w \wedge v] \in H^{p+q}$ makes H^* a RING (t.o., no mult. inverse)

\hookrightarrow Two spaces might have same cohomology groups but different ring structure!

Sample Calculation: show $H^1(S^1, \mathbb{R}) = \mathbb{R}$

- We'll need Poincaré's Lemma: $\forall M$ is contractible to a pt, all closed forms on M are exact.
- S^1 has dim 1, so if $w \in \mathcal{R}^1(M)$, $dw \in \mathcal{R}^2(M) \rightarrow dw = 0$
 \rightarrow all 1-forms on S^1 are closed.
- w exact ($w = d\gamma$) $\Rightarrow \int_{S^1} w = 0$ by Stokes's Thm

Claim: $\int_{S^1} w = 0 \Rightarrow w$ exact

Proof: Consider S^1 with one point deleted: $\tilde{S}^1 = S^1 - \{p\}$.

$$\int_{S^1} w = 0 \Rightarrow \int_{S^1 - \{p\}} w = 0 \text{ since } \{p\} \text{ has measure } 0$$

Since \tilde{S}^1 is contractible, $w = df$ on \tilde{S}^1 . Since f is C^∞ , it must be periodic. Hence $w = df$ is defined on whole S^1 . \square

- Classify members of $H^1(S^1, \mathbb{R})$: say w, w' are closed but not exact, i.e. $dw \neq 0 \Rightarrow \int_c w \neq 0 \Rightarrow$ can define $c = \frac{\int_{S^1} w}{\int_{S^1} w'} \in \mathbb{R}$

Then $\int (w - cw') = 0 \Rightarrow$ different elements of $H^1(S^1, \mathbb{R})$ differ only by a "real-number"

$$\Rightarrow \boxed{H^1(S^1, \mathbb{R}) = \mathbb{R}}$$