

REMARKS ON SECTION \rightarrow DISCUSSION

main goal is for us to talk to each other about material.

\rightarrow some kind of small contribution to your course grade

READ MATERIAL AHEAD OF TIME, BRING YOUR QUESTIONS

RULE: ITS FRIDAY AFTERNOON, YOU ALL HAVE BUSY LIVES.
I WON'T BE PERSONALLY OFFENDED IF YOU FALL ASLEEP

BUT: I RESERVE THE RIGHT TO TAKE A PICTURE
of you & POST IT ON MY FACEBOOK WALL.

A few remarks about VECTORS & TENSORS \rightarrow for course, will be useful later

IN LEC 1 I MADE A BIG DEAL ABOUT INDICES.
INDICES ARE KIND OF A CRUTCH THAT PHYSICISTS USE
& THAT MATHEMATICIANS KIND OF LOOK DOWN UPON.

THE ACTUAL THINGS WE CARE ABOUT ARE USUALLY SCALARS.

eg: STRESS TENSOR: HOW MUCH "P_z" EMITTED IN \hat{x} DIR?

$$T_{zx} = \hat{e}_z \cdot T \cdot \hat{e}_x$$

SO MORE GENERALLY: HOW MUCH MOMENTUM IN DIR \hat{u}_1
IS EMITTED IN THE \hat{u}_2 DIR?

$$= \hat{u}_1 \cdot T \cdot \hat{u}_2$$

NOW LET'S BE MORE GROWN UP W/ INDICES.

CONVENTION CHOICE: COLUMN VECTOR HAS ~~LOWER~~ ^{UPPER} INDEX: \vec{v}^i
ROW VECTOR HAS ~~UPPER~~ ^{LOWER} INDEX: \vec{v}_i

$$\text{DOT PRODUCTS: } (\underline{W}^T) \cdot \underline{V} = \sum_i W_i^{\text{up}} V_i^{\text{down}}$$

allowed contractions of indices
only: go from top ~~up~~ to bot. ~~down~~

So: $W_i V_i$ is NOT ALLOWED AS A SCALAR!
(btw: $W_i V_j$ is a VALID TENSOR)

note index structure!

ROTATIONS

$$V^i \rightarrow V'^i = R^i_j V^j$$

$$W_j \rightarrow W'_j = W_j R^j_i = R^j_i W_j$$

⇒ UPPER & LOWER INDICES TRANSFORM DIFFERENTLY!

↳ THIS IS PRECISELY WHAT'S REQUIRED TO KEEP INNER PRODUCT INVARIANT

~~$R^i_j R^j_k$~~ ~~$R^j_i R^i_k$~~ ... why?

DOT/INNER PRODUCTS ↔ "THE METRIC"

START W/ VECTORS: W^i, V^i . HOW DO WE FORM A SCALAR?
NEED TO LOWER THE INDEX SOMEHOW

↳ GO FROM VECTOR → DUAL VECTOR
QM: BRA → KET
GR: VECTOR → ONE-FORM

THIS IS DONE W/ THE METRIC TENSOR: g_{ij}

$$\underline{V} \cdot \underline{W} = (\underline{V}^T \underline{W}) = \underbrace{g_{ij}}_{V_i} V^j W^i$$

NOTE: METRIC DOES NOT TRANSFORM (DESPITE HAVING INDICES)
(BY DEFINITION)

$$\hookrightarrow R^k_i R^l_j g_{kl} = g_{ij}, \text{ also: } g_{ij} = g_{ji}$$

$$\begin{aligned} \underline{V} \cdot \underline{W} &= g_{ij} V^j W^i \rightarrow g_{ij} (R^j_k V^k) (R^i_l W^l) \\ &= V^k \underbrace{R^j_k g_{ij} R^i_l}_{R_{ik}} W^l \\ &= R_{ik} R^i_l \\ &\sim R^T R \quad \checkmark \end{aligned}$$

also inverse metric: $g^{ij} = g^{-1}$ s.t. $g^{ij} g_{jk} = \delta^i_k$

IN 3D EUCLIDEAN SPACE w/ CARTESIAN COORDINATES: $g_{ij} = \delta_{ij}$

4D = RELATIVITY

NON-EUCLIDEAN
= GENERAL RELATIVITY

also in this class:
3D NON-CARTESIAN COORDS
FOR EUCLIDEAN SPACE.

Why is it called a METRIC? IT MEASURES DISTANCE.
AN ALTERNATE WAY OF WRITING IT IS:

$$dl^2 = \underline{dl} \cdot \underline{dl} = g_{ij} dx^i dx^j = dx^2 + dy^2 + dz^2$$

BUT WE KNOW THIS IS DIFFERENT FOR DIFF COORDS!

$$dl^2 = \cancel{dr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2$$
$$= dp^2 + p^2 dt^2 + dz^2$$

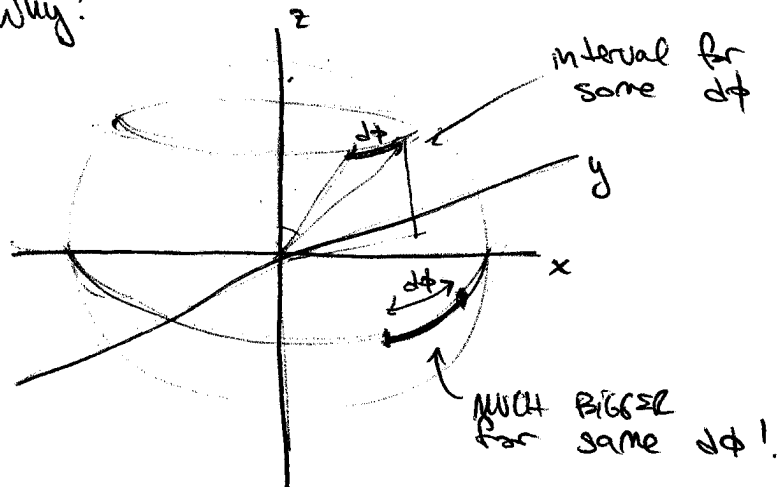
SO, eg, IN SPHERICAL COORDINATES:

ORTHOGONAL BASIS
 $\Rightarrow g$ IS DIAGONAL

$$g_{ij} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$

depends on position!

Why?



[NOW I APOLOGIZE THAT I HAVE TO BE A LITTLE SKETCHY;
FOR MORE BACKGROUND REFER TO YOUR FAVORITE DIFFERENTIAL
GEOMETRY TEXT.]

GRADIENT: WHAT KIND OF INDEX?

$\nabla \sim \frac{\partial}{\partial x^i} \Rightarrow \nabla_i$ ← this kind of heuristic logic drives mathematicians crazy
↑ $\forall x$, not just cartesian

BUT USUALLY WHEN WE TAKE GRADIENT, WE WANT A COLUMN VECTOR

so: $(\nabla f)^i = g^{ij} \nabla_j f$

this is where all the weird coefficients come from!

eg $\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \hat{\phi}$

THE OTHER DERIVATIVES ARE MORE COMPLICATED BECAUSE THEY ARE RELATED TO DIFFERENTIAL FORMS

the full expression for div :

see Frankel 2.9c
Beals 14

$\nabla \cdot V = \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^i} (\sqrt{\det g} V^i)$

↑
Why those determinants? VOLUME FORM
→ THESE COME FROM JACOBIANS OF THE VOLUME ELEM.

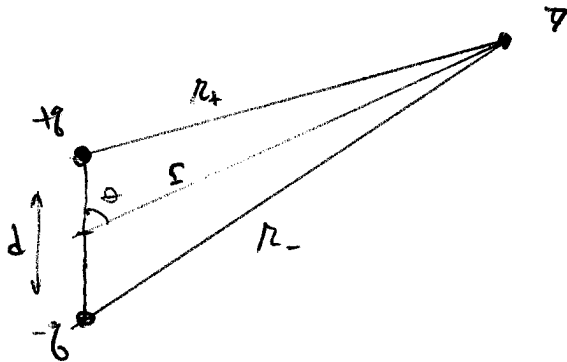
YOU DON'T NEED TO UNDERSTAND THE DERIVATION OF THIS

↳ BUT DO APPRECIATE THE GEOMETRIC FOUNDATION OF EVERYTHING WE'RE DOING!

by the way: $df = j \quad d^*f = 0$

OK. NOW WE MOVE ON: MULTIPLES.

REAL ELECTRIC DIPOLE (Griffiths 3.4)



INTUITION: FAR AWAY, LOOKS LIKE NO NET CHARGE BUT THERE'S A CHARGE "MOMENT" (CG "MOMENT" OF INERTIA, ETC...)

$\Phi_{\text{POINT CH}} \sim 1/r$

$\Phi_{\text{DIPOLE}} \sim \cos \theta / r^2$



because $1/r \rightarrow$ net source (b/c $\nabla 1/r \sim \delta$) so must be weaker than this

angular distribution

eg @ $\theta = \pi/2$ still DON'T SEE Φ BECAUS $+q \neq -q$ CAN'T CANCEL.

still $E = \nabla \Phi$, of course!

Physicist: WE MAKE THE RELEVANT TAYLOR EXPANSIONS!

[I think the dipole is usually taught w/ eg law of cosines & then Taylor expansion later]

WHAT IS EXPANDABLE? (SMALL):

d/r

so WE'RE THINKING OF ~~that~~ $d \ll r$ LIMIT.

I'M NOT GOING TO DO THE TRIG → SEE TEXTBOOK
YOU END UP WITH:

$$\Phi = \frac{2q(\frac{1}{2}) \cos \theta}{r^2} \equiv \frac{\mathbf{p} \cdot \hat{\mathbf{e}}_r}{r^2}$$

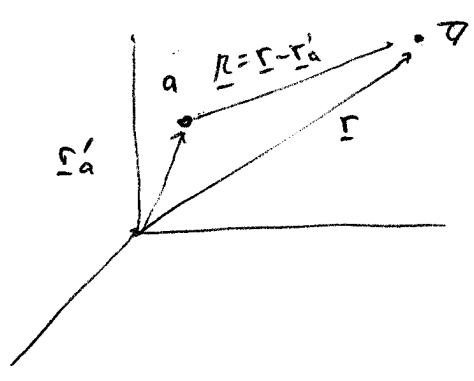
← up to 40's ; stuff

dipole moment

BUT MORE GENERALLY [see Heald + Marion 2.3]

$$\Phi_a = \underbrace{\Phi(\text{assuming } q \text{ @ ORIGIN})}_{\equiv \Phi_a^{(0)}} + \underbrace{\text{CORRECTIONS}}_{\text{TAYLOR EXPANSION IN } \underline{\Gamma}'_a \text{ (3D EXPANSION)}}$$

↑
contrib from ath charge in the config



R IS THE DISTANCE FOR THE $\Phi \sim 1/r$ LAW, BUT a IS NOT AT THE ORIGIN SO $R \neq r$.

SO TAYLOR: write $\Phi_a(\underline{r})$ for $\Phi_a(\underline{r}, \underline{\Gamma}'_a)$; evaluate @ $\underline{\Gamma}'_a = 0$

expansion point
↓ implicit

$$\Phi_a(\underline{r}) = \Phi_a^{(0)}(\underline{r}) + \underline{\Gamma}'_a \cdot \nabla' \Phi + \frac{1}{2} \underline{\Gamma}'_a^i \underline{\Gamma}'_a^j \nabla_i \nabla_j \Phi + \dots$$

↑
GRAD WRT $\underline{\Gamma}'_a$

SWITCH TO INDEX NOTATION... OTHERWISE HARD TO WRITE

↑
quadrupole

check: this is precisely "half" the dipole term in the simple system above!

$$\boxed{\Phi = \sum_a \Phi_a} \rightarrow \text{BECOMES INTEGRAL FOR CONTINUOUS DIST.}$$

WE'LL TALK ABOUT THIS MORE NEXT WK, AFTER YOU'VE HAD MORE
LECTURES (I HAVE MORE QUESTIONS) → A NEW HW. ☺

NOTE THAT WE'RE TAKING DERIVATIVES OF WHAT IS BASICALLY

$$\phi \sim \frac{1}{|\underline{r} - \underline{r}'|}$$

there is a very useful expansion of this function
in terms of LEGENDRE POLYNOMIALS:

$$\frac{1}{|\underline{r} - \underline{r}'|} = \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{r'}{r}\right)^l P_l(\cos \theta)$$

\uparrow \downarrow
 $\hat{r} \cdot \hat{r}'$

EACH TERM IS A
"NICE" FUNCTION r^{-n}
RATHER THAN $1/|\underline{r}'|$

AS YOU KNOW FROM QUANTUM,
 l IS RELATED TO ANGULAR
[MOMENTUM] SQ. .

$$\left. \begin{matrix} P_0 = 1 \\ P_1 = \cos \theta \end{matrix} \right\} \text{PRECISELY WHAT WE FOUND}$$

$$P_2 = \frac{1}{2}(3 \cos^2 \theta - 1) = \frac{1}{2}(3(\hat{r} \cdot \hat{r}')^2 - 1)$$

SO OFTEN ITS NICE TO WRITE
HIGHER PLE TERMS W/ A
LEGENDRE POLY.

$$= \frac{1}{2} (3 \hat{r}'_i \hat{r}'_j - \delta_{ij}) \hat{r}_i \hat{r}_j$$

$\underbrace{\hspace{10em}}$
 traceless matrix
 ("IRREDUCIBLE")

WHAT ARE THESE P_l 'S? THEY ARE JUST A BASIS FOR
THE ANGULAR PARTS OF 3D FUNCTIONS.

→ WELL, MORE APPROPRIATELY, THE Y_l^m 'S ARE THIS.

THIS IS A VECTOR SPACE (AS YOU LEARNED IN QUANTUM?!)
W/ ITS OWN METRIC, SENSE OF DUAL VECTORS, etc!!