



# Simplified Equation of Motion



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Only magnetic fields:

$$\vec{E} = 0$$

Mid-plane symmetry:  $B_x(x, y, s) = -B_x(x, -y, s)$ ,  $B_y(x, y, s) = B_y(x, -y, s)$

Linearization in :  $B_x(x, y, s) = \frac{p_0}{q} k y$ ,  $B_y(x, y, s) = \frac{p_0}{q} \frac{1}{\rho} + \frac{p_0}{q} k x$

Highly relativistic :  $\frac{p-p_0}{p_0} \rightarrow \frac{E-E_0}{E_0}$ ,  $\frac{v-v_0}{v_0} \rightarrow 0$

$$\underline{x'} = \frac{p_x}{p_z} = \frac{p_x}{\sqrt{(p_0+dp)^2 - p_x^2 - p_y^2}} =_1 \frac{p_x}{p_0} = \underline{a} \quad \Rightarrow \quad \underline{y' = b}$$

$$\underline{a'} = \frac{(\vec{p}' + p_s \kappa \vec{e}_x)_x}{p_0} = \frac{h}{p_0 v_s} \frac{d}{dt} p_x + \frac{p_s \kappa}{p_0} = -\frac{1+x\kappa}{p_0 v_s} q v_s B_y + \frac{p_s \kappa}{p_0}$$

$$= _1 \underline{-(1+x\kappa)(\kappa+kx) + (1+\delta)\kappa} = \underline{-x(\kappa^2+k) + \delta\kappa} \quad \Rightarrow \quad \underline{b' = -ky}$$

$$\tau' = \frac{d(t-t_0)}{ds} \frac{E_0}{p_0} = \left( \frac{1}{v_0} - \frac{h}{v_s} \right) \frac{E_0}{p_0} =_1 -x\kappa, \quad \underline{\delta' = 0}$$

Hamiltonian:

$$H = \frac{1}{2} a^2 + \frac{1}{2} b^2 + \frac{1}{2} k(x^2 - y^2) + \frac{1}{2} \kappa^2 x^2 - \kappa x \delta$$



# Matrix Solutions



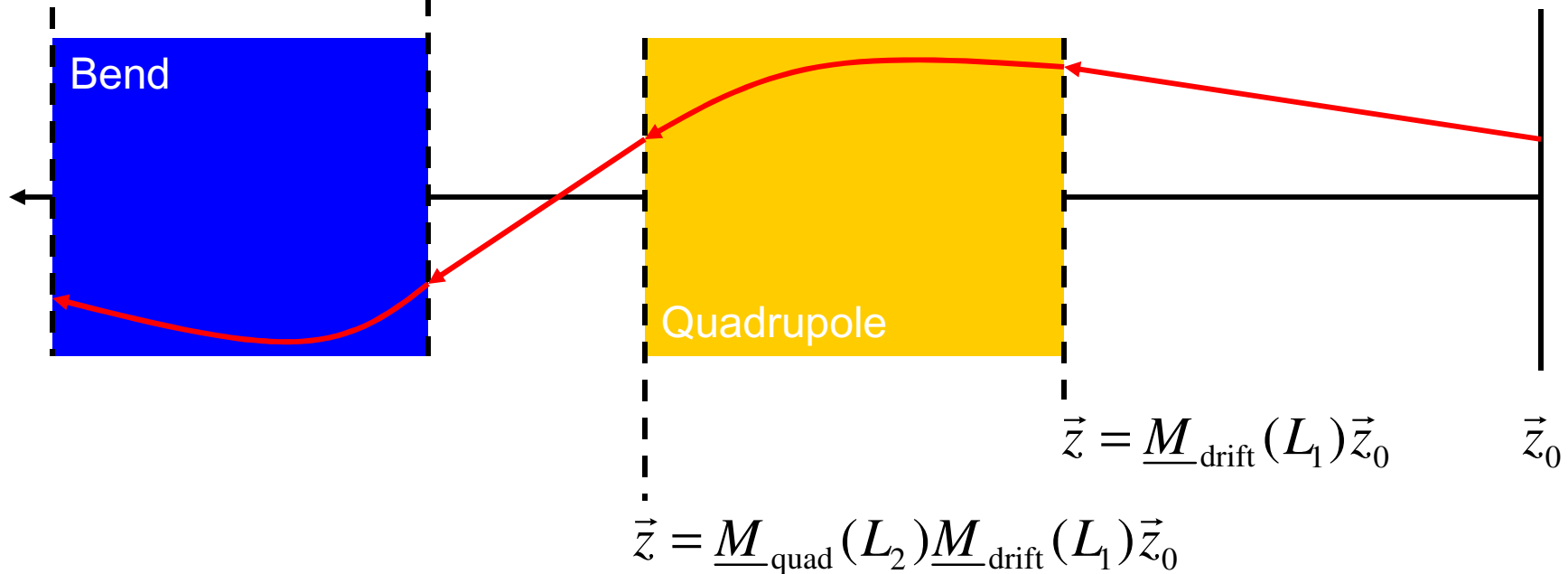
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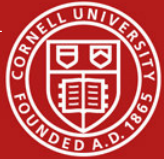
Linear equation of motion:  $\vec{z}' = \underline{F}(s)\vec{z}$

Matrix solution of the starting condition  $\vec{z}(0) = \vec{z}_0$

$$\vec{z} = \underline{M}_{\text{bend}}(L_4)\underline{M}_{\text{drift}}(L_3)\underline{M}_{\text{quad}}(L_2)\underline{M}_{\text{drift}}(L_1)\vec{z}_0$$

$$\vec{z} = \underline{M}_{\text{drift}}(L_3)\underline{M}_{\text{quad}}(L_2)\underline{M}_{\text{drift}}(L_1)\vec{z}_0$$





# The Drift



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$$\begin{pmatrix} x' \\ a' \\ y' \\ b' \\ \tau' \\ \delta' \end{pmatrix} = \begin{pmatrix} a \\ 0 \\ b \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Note that in nonlinear expansion  $x' \neq a$  so that the drift does not have a linear transport map even though  $x(s) = x_0 + x'_0 s$  is completely linear.

$$\begin{pmatrix} x \\ a \\ y \\ b \\ \tau \\ \delta \end{pmatrix} = \begin{pmatrix} x_0 + sa_0 \\ a \\ y_0 + sb_0 \\ b_0 \\ \tau_0 \\ \delta_0 \end{pmatrix} = \begin{pmatrix} 1 & s & \underline{0} & \underline{0} \\ 0 & 1 & \underline{0} & \underline{0} \\ \underline{0} & 1 & s & \underline{0} \\ 0 & 1 & \underline{0} & \underline{0} \\ \underline{0} & \underline{0} & 1 & 0 \\ \underline{0} & \underline{0} & 0 & 1 \end{pmatrix} \vec{z}_0$$



# The Dipole Equation of Motion



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$$x'' = -x \kappa^2 + \delta \kappa$$

$$y'' = 0$$

$$\tau' = -x \kappa$$

Homogeneous solution:

$$x_H'' = -x_H \kappa^2 \Rightarrow x_H = A \cos(\kappa s) + B \sin(\kappa s) \quad (\text{natural ring focusing})$$

Variation of constants:

$$x = A(s) \cos(\kappa s) + B(s) \sin(\kappa s)$$

$$x' = -A \kappa \sin(\kappa s) + B \kappa \cos(\kappa s) + \underbrace{A' \cos(\kappa s) + B' \sin(\kappa s)}_{\equiv 0}$$

$$x'' = -\kappa^2 x - \underbrace{A' \kappa \sin(\kappa s) + B' \kappa \cos(\kappa s)}_{=\delta \kappa} = -\kappa^2 x + \delta \kappa$$

$$\begin{pmatrix} \cos(\kappa s) & \sin(\kappa s) \\ -\sin(\kappa s) & \cos(\kappa s) \end{pmatrix} \begin{pmatrix} A' \\ B' \end{pmatrix} = \begin{pmatrix} 0 \\ \delta \end{pmatrix}$$



# The Dipole



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$$\begin{pmatrix} A' \\ B' \end{pmatrix} = \begin{pmatrix} \cos(\kappa s) & -\sin(\kappa s) \\ \sin(\kappa s) & \cos(\kappa s) \end{pmatrix} \begin{pmatrix} 0 \\ \delta \end{pmatrix}$$

$$\begin{pmatrix} A \\ B \end{pmatrix} = \delta \kappa^{-1} \begin{pmatrix} \cos(\kappa s) \\ \sin(\kappa s) \end{pmatrix} + \begin{pmatrix} A_H \\ B_H \end{pmatrix} \quad \text{with} \quad x = A \cos(\kappa s) + B \sin(\kappa s)$$

$$\tau' = -x \kappa$$

$$\underline{M} = \begin{pmatrix} \cos(\kappa s) & \frac{1}{\kappa} \sin(\kappa s) & \underline{0} & 0 & \kappa^{-1}[1 - \cos(\kappa s)] \\ -\kappa \sin(\kappa s) & \cos(\kappa s) & \underline{0} & 0 & \sin(\kappa s) \\ \underline{0} & \underline{0} & 1 & s & \underline{0} \\ -\sin(\kappa s) & \kappa^{-1}[\cos(\kappa s) - 1] & 0 & 1 & \kappa^{-1}[\sin(\kappa s) - s \kappa] \\ 0 & 0 & \underline{0} & 0 & 1 \end{pmatrix}$$



# Time of Flight from Symplecticity



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$$\underline{M} = \begin{pmatrix} \underline{M}_4 & \vec{0} & \vec{D} \\ \vec{T}^T & 1 & M_{56} \\ \vec{0}^T & 0 & 1 \end{pmatrix} \quad \text{is in SU(6) and therefore} \quad \underline{M} \underline{J} \underline{M}^T = \underline{J}$$

$$\begin{pmatrix} \underline{M}_4 \underline{J}_4 & -\vec{D} & \vec{0} \\ \vec{T}^T \underline{J}_4 & -M_{56} & 1 \\ \vec{0}^T & -1 & 0 \end{pmatrix} \begin{pmatrix} \underline{M}_4^T & \vec{T} & \vec{0} \\ \vec{0}^T & 1 & 0 \\ \vec{D}^T & M_{56} & 1 \end{pmatrix} = \begin{pmatrix} \underline{J}_4 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} \underline{M}_4 \underline{J}_4 \underline{M}_4^T & \underline{M}_4 \underline{J}_4 \vec{T} - \vec{D} & \vec{0} \\ \vec{T}^T \underline{J}_4 \underline{M}_4^T + \vec{D}^T & 0 & 1 \\ \vec{0}^T & -1 & 0 \end{pmatrix} = \begin{pmatrix} \underline{J}_4 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\vec{T} = -\underline{J}_4 \underline{M}_4^{-1} \vec{D}$$

It is sufficient to compute the 4D map  $\underline{M}_4$ , the Dispersion  $\vec{D}$  and the time of flight term  $M_{56}$



# The Quadrupole (Homework)



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$$x'' = -x k$$

$$y'' = y k$$

$$\underline{M}_4 = \begin{pmatrix} \cos(\sqrt{k} s) & \frac{1}{\sqrt{k}} \sin(\sqrt{k} s) & & \underline{0} \\ -\sqrt{k} \sin(\sqrt{k} s) & \cos(\sqrt{k} s) & & \\ & \underline{0} & \cosh(\sqrt{k} s) & \frac{1}{\sqrt{k}} \sinh(\sqrt{k} s) \\ & & \sqrt{k} \sinh(\sqrt{k} s) & \cosh(\sqrt{k} s) \end{pmatrix}$$

As for a drift:

$$\vec{D} = \vec{0} \Rightarrow \vec{T} = \vec{0}$$

$$M_{56} = 0$$

For  $k < 0$  one has to take into account that

$$\cos(\sqrt{k} s) = \cosh(\sqrt{|k|} s), \quad \sin(\sqrt{k} s) = i \sinh(\sqrt{|k|} s)$$

$$\cosh(\sqrt{k} s) = \cos(\sqrt{|k|} s), \quad \sinh(\sqrt{k} s) = i \sin(\sqrt{|k|} s)$$



# The Combined Function Bend (Homework)



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$$x'' = -x \underbrace{(\kappa^2 + k)}_K + \delta \kappa$$

$$y'' = y k, \quad \tau' = -\kappa x$$

$$\underline{M}_6 = \begin{pmatrix} \underline{M}_x & \underline{0} & \vec{0} \vec{D} \\ \underline{0} & \underline{M}_y & \underline{0} \\ \underline{T} & \underline{0} & \underline{M}_\tau \end{pmatrix}$$

$$\underline{M}_x = \begin{pmatrix} \cos(\sqrt{K} s) & \frac{1}{\sqrt{K}} \sin(\sqrt{K} s) \\ -\sqrt{K} \sin(\sqrt{K} s) & \cos(\sqrt{K} s) \end{pmatrix}$$

$$\underline{M}_y = \begin{pmatrix} \cosh(\sqrt{k} s) & \frac{1}{\sqrt{k}} \sinh(\sqrt{k} s) \\ \sqrt{k} \sinh(\sqrt{k} s) & \cosh(\sqrt{k} s) \end{pmatrix}$$

$$\vec{D} = \begin{pmatrix} \frac{\kappa}{K} [1 - \cos(\sqrt{K} s)] \\ \frac{\kappa}{\sqrt{K}} \sin(\sqrt{K} s) \end{pmatrix}$$

$$\underline{M}_\tau = \begin{pmatrix} 1 & M_{56} \\ 0 & 1 \end{pmatrix}$$

$$M_{56} = \frac{\kappa^2}{K\sqrt{K}} [\sin(\sqrt{K} s) - \sqrt{K} s]$$

$\underline{T}$  from symplecticity

## Options:

- For  $k > 0$ :  
focusing in x, defocusing in y.
- For  $k < 0, K < 0$ :  
defocusing in x, focusing in y.
- For  $k < 0, K > 0$ :  
weak focusing in both planes.