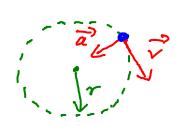
Recape

· Forces in uniform circular motion:



•
$$\overline{ZF}_{on object = ma}$$
 with $|\overline{a}| = \frac{\nu^2}{\tau}$

and ZFon object and a : point to center of circle, L to path

never show $m\frac{V^2}{T}$ on a FBDV \bar{a} is the result of the external forces on the object P

· Kinetic Energy:
$$K = \frac{1}{2} m v^2$$

• Work: energy transferred to or from an object by force for a constant force: $W = \vec{F} \cdot \vec{d} = Fd \cos \phi = F_{ii} d = Fd_{ii}$ "dot"

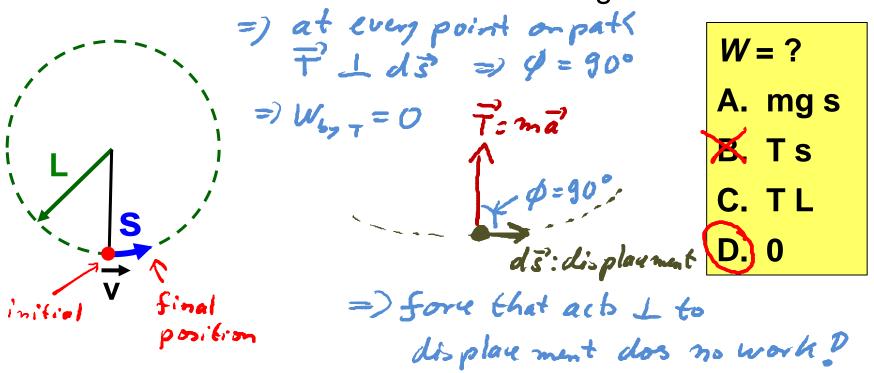
product of \vec{F} II to \vec{d} of \vec{d} II to \vec{F}

Today:

- Work and Energy:
 - Work done by a single force
 - Work-kinetic energy theorem
 - Work done by gravity, friction…

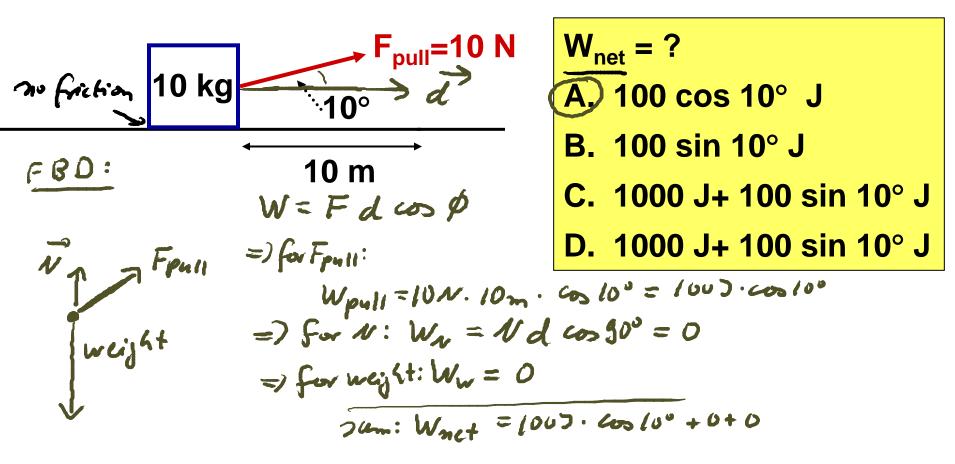


A **ball** of **mass** m is swung at the end of the rope in a **horizontal circle**. Its **speed** v is constant and the length of the rope is L. Note: v = const = 0 T = const = 0 work done What work W is done by the tension T in the rope when the mass moves a small distance s along the circle?



Work done by a single, constant force on object: d: displacement vector d1167 = d cos \$ $= \overrightarrow{r}_2 - \overrightarrow{r}_1$ component of d Ø: angle between F note: if $\phi = 90^\circ = 1$ Wby force on = 0

A 10 kg crate is pulled 10 m along a frictionless horizontal floor by a force F_{pull} =10 N applied at an angle of 10° with respect to the horizontal, as shown. What is the net work done on the crate by all the forces that act on it?



• Work done by a single constant force on object

angle between F and d

Why force on = Fd cos $\phi = F_{ij} d = F d_{ij}$ object Mathematical Shorthand: W = F d "dot "product of two vectors Y = Fd cos p reangle between the two vectors use this $= E = E_X d_X + E_Y d_Y$ mote:
if you know $\int_{-\infty}^{\infty} (anbe < 0)$ Componen 5 of vectors works for any coordinate system

· Work done by multiple forces (constant) acting on an object:

Some object -> some displayment d $W_{net} = W_1 + W_2 + ... = F_1 \cdot d + F_2 \cdot d + ...$

 $= (\vec{z}\vec{F}) \cdot \vec{d} = \vec{F}_{net} \cdot \vec{d} = F_{net} d \cos \phi$

angle between Finet and d

Work - Kinetic Energy Theorem:

- Work: Energy transferred to or from an object by force
- Kinetic enesy: $JY = \frac{1}{2} m v^2$

Note: DXCO or DX>0 possible!

check Work - Deinetie Entry theorem: Vi,x, T Fpull OH= H, - H; = = m /2 - = m /ix y weight $v_{f,x}$ = Wnet = Wn + Wweist + Wpoll weight f, x = $\vec{F}_{pull} \cdot \vec{d} = F_{pull} \cdot \vec{d}$ = $F_{pull} \cdot \vec{d}$ = $F_{pull} \cdot \vec{d}$ | f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f = f =) $\frac{1}{2}m(V_{f,X}-V_{i,X})=F_{pull,X}d=ma_Xd$ =) $V_{5,1} - V_{i,x} = 2a_x d = 2a_x Dx$ } nothing new. =) same as Newton's laws, but work/Kinetic helps to solve some problems much lasies than Newton's Laws!

A car of mass m traveling at a speed v_i is braked to a stop by a constant force F.

What is the stopping distance d of the car? (Use energy/work concepts to solve, not NII.)

Use D
$$\exists Y = W_{nct} = \exists W_i \left(\begin{array}{c} W_{orh} - H_{inr}K_i \\ e_{nej} + H_{err}M_i \end{array} \right) d = ?$$

FBD of car $W_{weij} : t = 0$ $C = qv^{\circ}$ A. F/v_i

B. mv_i/F
 $V_i = F_{orb} = F_{orb$

Work done by specific forcs:

1) Work done by gravity:

1 + y = important D

- y: [m]

Weight=mg'

Or

× Yc

movs down 3 Wg > 0
movs up =) Wg < 0

Why growt, = $\vec{F} \cdot \vec{d}$ of for down on which = $\vec{F} \cdot \vec{d}$ cos $\phi = \vec{F} \cdot \vec{d}$ =-mg Dy = 0 y c 0 her = - mg (75-/i) = - mg (vetical displayment) for +y un!