

Recap:

• Momentum: $\vec{p} = m\vec{v}$

$$\vec{F}_{\text{net, ext}} = \sum \vec{F}_{\text{ext}} = m_{\text{total}} \vec{a}_{\text{com}} = \frac{d\vec{p}_{\text{total}}}{dt}$$

\Rightarrow If $\vec{F}_{\text{net, ext}} = 0$: $\vec{p}_{\text{total}} = \underbrace{\vec{p}_1 + \vec{p}_2 + \vec{p}_3 + \dots}_{\text{System of objects}} = \text{const}$ } Momentum is conserved!

• Collisions: Brief, intense interaction between two (or more) objects.

"Intense": external forces can usually be neglected during time of collision

$$\Rightarrow \text{If } \sum \vec{F}_{\text{ext}} = \frac{d\vec{p}_{\text{total}}}{dt} = 0$$

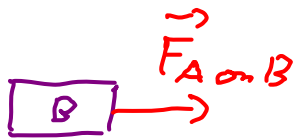
$$\Rightarrow \vec{p}_{\text{total}} = \text{const during any type of collision!}$$

Impulse:

$$\vec{J}_{\text{on object during collision}} = \int_{\text{time of collision}} \vec{F}_{\text{coll}}(t) dt = \vec{F}_{\text{avg}} \Delta t_{\text{coll}} = \underline{\underline{\Delta \vec{p}}} = \left(\begin{array}{l} \text{area under} \\ \text{F-t graph} \end{array} \right)$$

↑ not F-x!

Example:



N III: $\vec{F}_{B \text{ on } A} = -\vec{F}_{A \text{ on } B} \Rightarrow \int_{\Delta t_{\text{coll}}} \vec{F}_{B \text{ on } A} dt = - \int_{\Delta t_{\text{coll}}} \vec{F}_{A \text{ on } B} dt$

$$\Rightarrow \vec{J}_{\text{on A}} = -\vec{J}_{\text{on B}}$$

$$\Rightarrow \Delta \vec{p}_A = -\Delta \vec{p}_B$$

$$\Rightarrow \Delta \vec{p}_A + \Delta \vec{p}_B = 0 \Rightarrow \vec{p}_{\text{total}} = \text{const}$$

Studying Collisions:

- General (always true):

$$\text{If } \sum \vec{F}_{\text{ext on system during collision}} = \frac{d\vec{P}_{\text{total}}}{dt} = 0 \quad \left(\begin{array}{l} \text{or neglectable} \\ \text{compared with} \\ \text{internal forces} \\ \text{during collision} \end{array} \right)$$

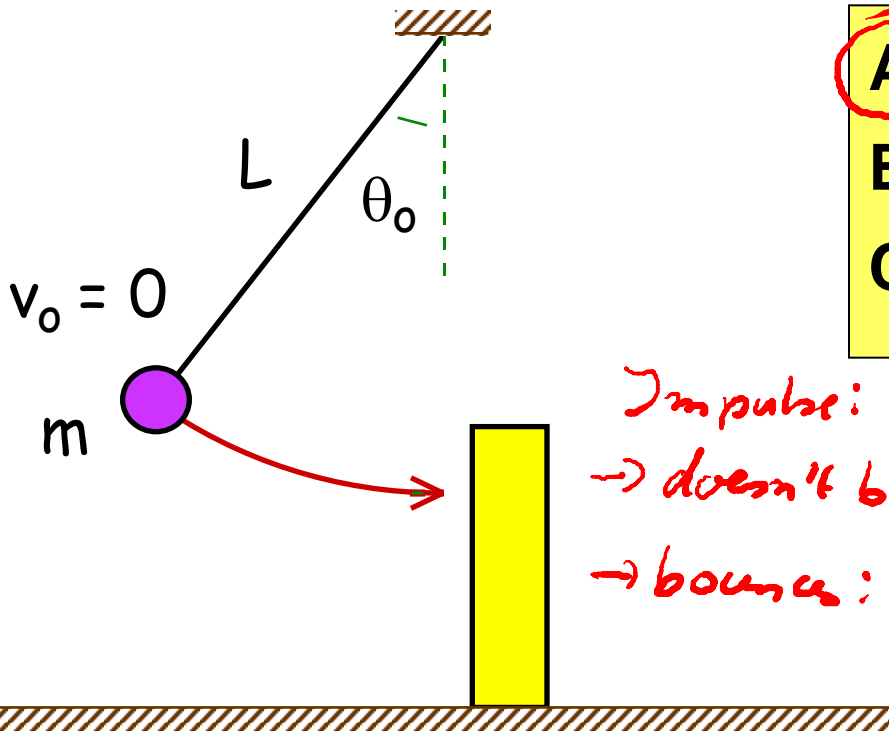
$\Rightarrow \vec{P}_{\text{total}}$ of system is conserved (constant)!

"system" = two (or more) objects, colliding

$$\begin{aligned} \Rightarrow \quad & \vec{P}_{\text{total, initial}} = \vec{P}_{\text{total, final}} \\ & \vec{P}_{\text{total, before coll.}} = \vec{P}_{\text{total, after coll.}} \\ & \vec{P}_{1,i} + \vec{P}_{2,i} + \dots = \vec{P}_{1,f} + \vec{P}_{2,f} + \dots \end{aligned} \quad \left. \begin{array}{l} \text{always} \\ \text{true,} \\ \text{for} \\ \text{any} \\ \text{type} \\ \text{of collision} \end{array} \right\}$$

A ball of mass m , attached to a string of length L , is released from rest at angle θ_0 and then strikes a standing wooden block.

Is the block more likely to tip over if the ball bounces off of the block or if the ball doesn't bounce?

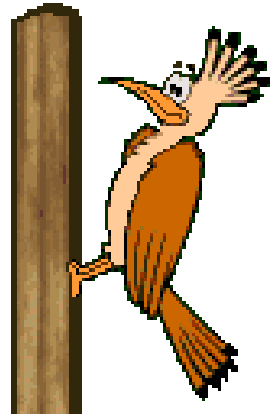


- A. Bounces**
- B. Doesn't bounce**
- C. Equally likely in both cases**

Impulse: $\vec{J} = \vec{F}_{avg} \Delta t_{coll} = \Delta \vec{p}$
 \rightarrow doesn't bounce: $\Delta \vec{p} = \vec{p}_f - \vec{p}_i = -\vec{p}_i$ ←
 \rightarrow bounce: $\Delta \vec{p} = \vec{p}_f - \vec{p}_i = -\vec{p}_i - \vec{p}_i$ ←←
 larger change
 \Rightarrow larger impulse on block

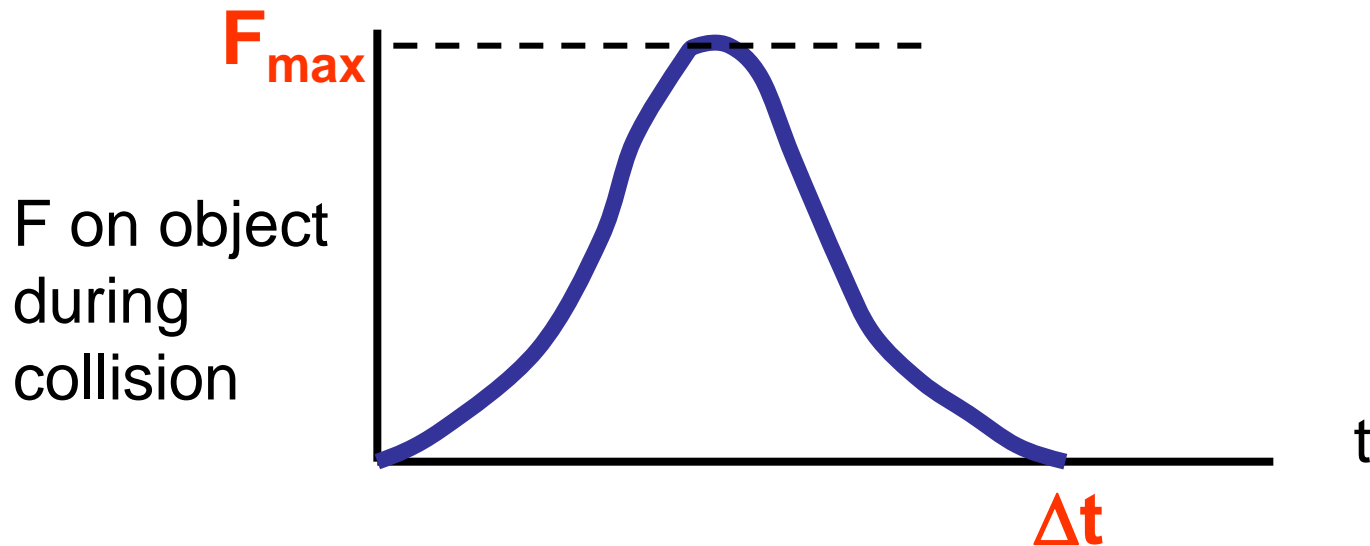
Today:

- **Collisions, Collisions, Collisions...**
- **Airbags and shock absorbers**
- **The woodpecker (why don't they knock themselves silly)**
- **The gravitational “Slingshot” effect**
- **Types of collisions: elastic and inelastic**



Shock Absorbers:

$$\text{Impulse } J = \int F \, dt = F_{\text{avg}} \Delta t = \Delta p$$



Key idea: Reduce F_{avg} , F_{max} by making Δt of collision longer!

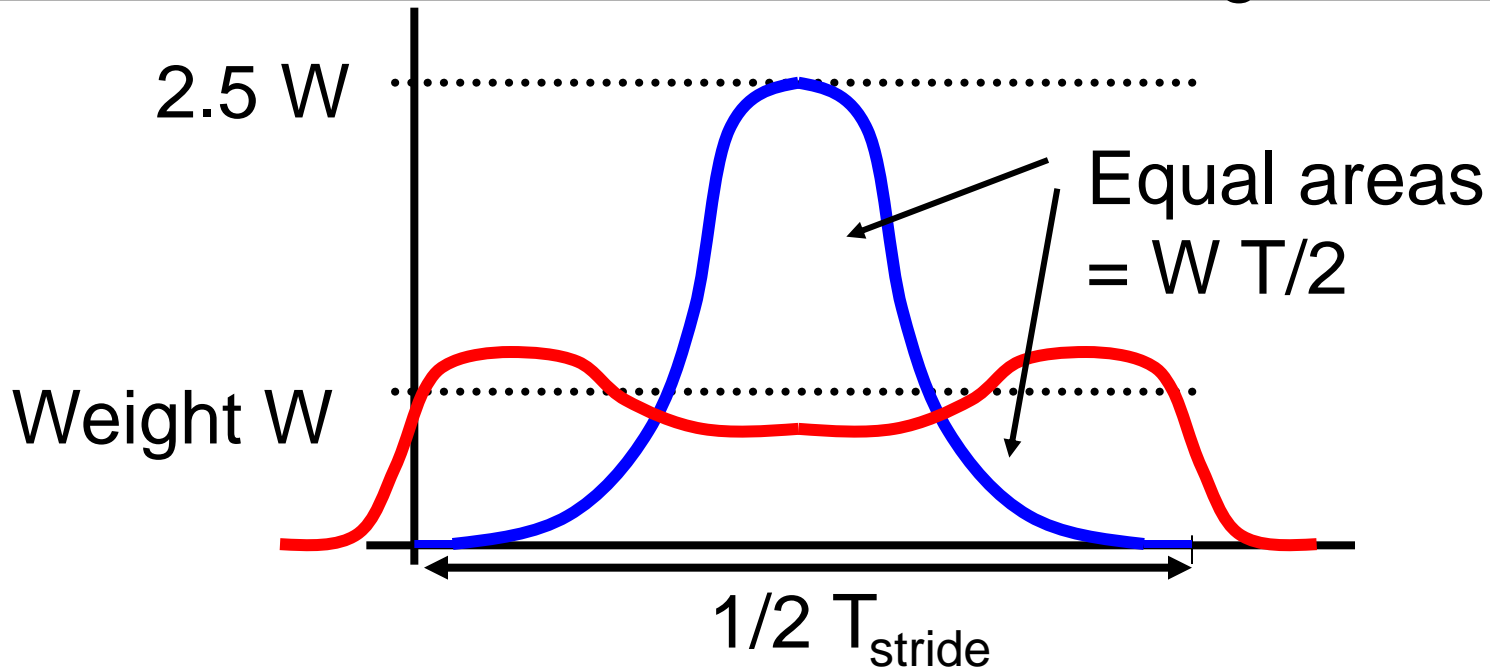
Foot arches

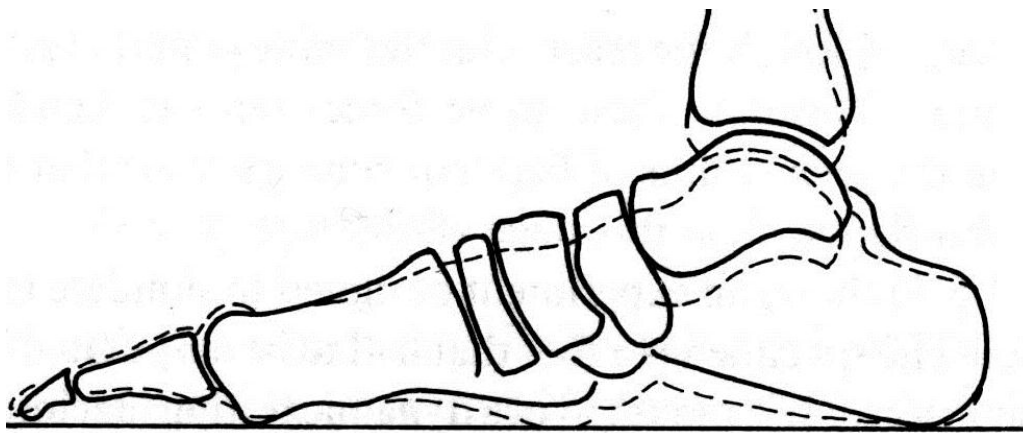
(padded running shoes, paw pads...)

Walking: at least one foot in contact with ground at all times

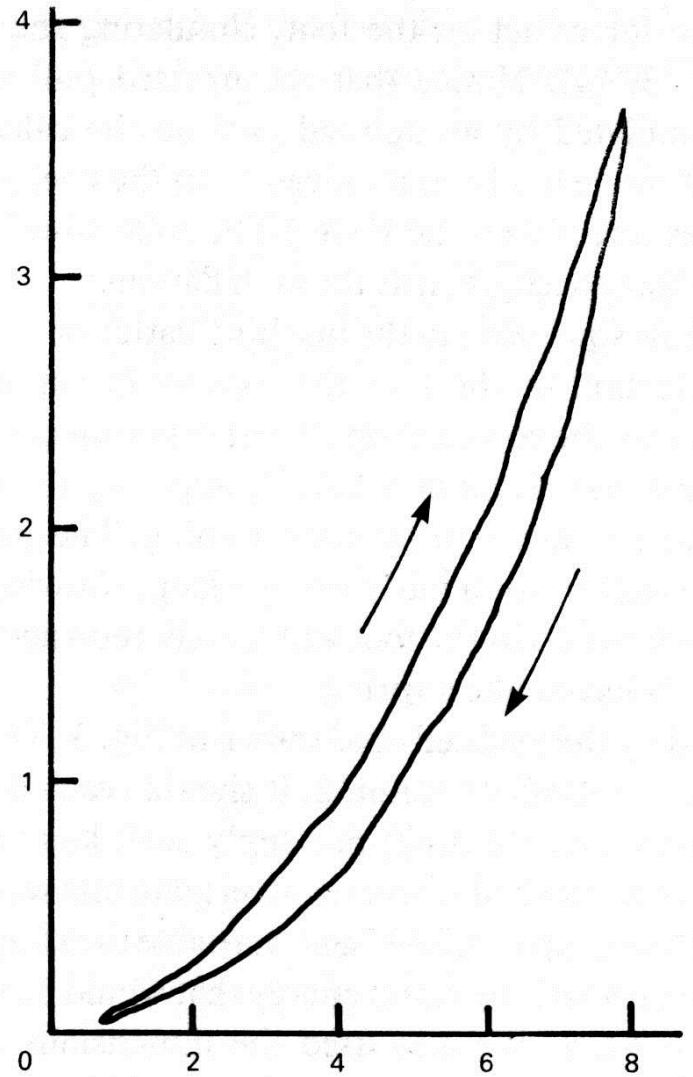
Running: ~ a series of leaps

Vertical force exerted on one foot during one stride:





Load [kN]



Displacement [mm]

Boxers:



$$m_{\text{arm}} \sim 7 \text{ kg}$$

$$v_{\text{arm}} \sim 7 \text{ m/s}$$

$$\Rightarrow \text{Impulse } J = \Delta p \sim m_{\text{arm}} v_{\text{arm}} \sim 49 \text{ kg m/s}$$

$$\text{impact time } \Delta t \sim 0.01 \text{ s} \Rightarrow F_{\text{avg}} \sim J/\Delta t \sim 4900 \text{ N}$$

$$m_{\text{arm}} \sim 7 \text{ kg}$$

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$$\text{impact time } \Delta t \sim 0.01 \text{ s} \Rightarrow F_{\text{avg}} \sim J/\Delta t \sim 4900 \text{ N}$$

$$m_{\text{head}} \sim 6 \text{ kg}$$

$$\Rightarrow a_{\text{head}} = F/m_{\text{head}} \sim 800 \text{ m/s}^2 \sim 80 \text{ g!}$$

- enough to cause unconsciousness
~ 40% of fatal blow

Woodpeckers:



During "collision" with a tree,

$$a_{\text{head}} \sim 600 - 1500 \text{ g!!}$$

How do they survive?

- $F_{\text{brain}} = m_{\text{brain}} a_{\text{brain}}$ is much smaller.
- $m_{\text{brain}}/A_{\text{brain}}$ much smaller for woodpeckers
 $\Rightarrow F_{\text{brain}}/A_{\text{brain}} = \text{"pressure"}$ is much smaller
- Jaw muscles act as shock absorbers
- Straight head trajectory reduces damaging rotations

Studying Collisions:

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$\Rightarrow \vec{P}_{\text{total}}$ of system is conserved (constant)!

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$$\begin{aligned} \Rightarrow \quad & \vec{P}_{\text{total, initial}} = \vec{P}_{\text{total, final}} \\ & \vec{P}_{\text{total, before coll.}} = \vec{P}_{\text{total, after coll.}} \\ & \vec{P}_{1,i} + \vec{P}_{2,i} + \dots = \vec{P}_{1,f} + \vec{P}_{2,f} + \dots \end{aligned} \quad \left. \begin{array}{l} \text{always} \\ \text{true,} \\ \text{for} \\ \text{any} \\ \text{type} \\ \text{of collision} \end{array} \right\}$$

- Types of collisions:

• Elastic Collisions:

$$\boxed{\sum K_i = \sum K_f}$$

$$\underbrace{\text{total KE}}_{\text{before collision}} = \underbrace{\text{total KE}}_{\text{after collision}}$$

} Kinetic energy is also conserved during the collision, in addition to total momentum

• Inelastic Collision:

$$\sum K_i > \sum K_f$$

} Some of the initial KE is lost while total momentum is conserved

- special case: sticking collision:

$$\boxed{V_{s,1} = V_{s,2}}$$

} have the largest possible loss in kinetic energy ΔK_{loss}

• Superelastic Collision:

$$\sum K_i < \sum K_f$$

} objects explode during collision...

Case A: Elastic collisions: kinetic energy is conserved in addition to momentum

$$\vec{P}_{\text{total}} = \text{const}$$

$$\sum K_i = \sum K_f$$

Case A-1: 1-D elastic collision with object "2" at rest (stationary target)

before:



after:



- Cons. of momentum:

$$m_1 v_{i,1} + m_2 v_{i,2} = m_1 \underline{v_{f,1}} + m_2 \underline{v_{f,2}}$$
 - Cons. of KE:

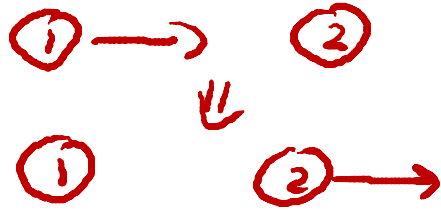
$$\frac{1}{2} m_1 v_{i,1}^2 + \frac{1}{2} m_2 v_{i,2}^2 = \frac{1}{2} m_1 v_{f,1}^2 + \frac{1}{2} m_2 v_{f,2}^2$$
- \Rightarrow 2 equ, 2 unknowns ($v_{f,1}, v_{f,2}$)

\Rightarrow solve:

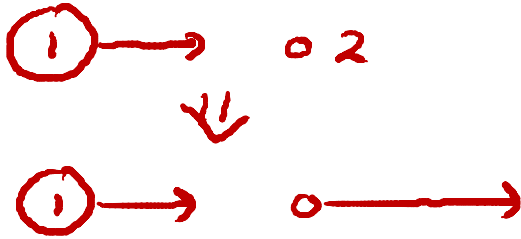
$$v_{f,1} = \frac{m_1 - m_2}{m_1 + m_2} v_{i,1}$$

$$v_{f,2} = \frac{2 m_1}{m_1 + m_2} v_{i,1}$$

\Rightarrow if $m_1 = m_2$



\Rightarrow if $m_1 \gg m_2$



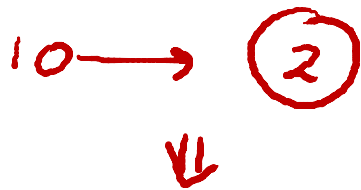
$$V_{S,1} = 0$$

$$V_{S,2} = V_{i,1}$$

$$V_{S,1} = \frac{m_1 - m_2}{m_1 + m_2} v_{i,1} \approx v_{i,1} \left. \vphantom{\frac{m_1 - m_2}{m_1 + m_2}} \right\} \begin{array}{l} \text{large} \\ \text{mass} \\ \text{keep going} \end{array}$$

$$V_{S,2} = \frac{2m_1}{m_1 + m_2} v_{i,1} \approx 2v_{i,1}$$

\Rightarrow if $m_1 \ll m_2$



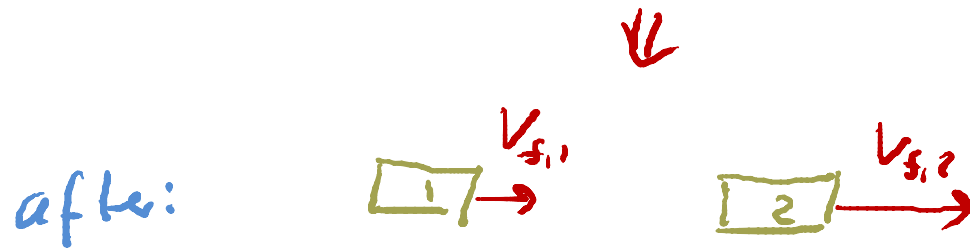
$$V_{S,1} = \frac{m_1 - m_2}{m_1 + m_2} v_{i,1} \approx -1 \cdot v_{i,1} \left. \vphantom{\frac{m_1 - m_2}{m_1 + m_2}} \right\} \begin{array}{l} \text{bounces} \\ \text{off} \\ \text{mass 2} \end{array}$$

$$V_{S,2} = \frac{2m_1}{m_1 + m_2} v_{i,1} \rightarrow \text{tiny}$$

02 13:59:33 PLAY-001770
FWD30 -0001.7700sec

000000 A: 00.0 B: 00.0
1/1000 END 1000FPS

Case A-2: 1-D elastic, both objects moving before collision



• Cons. of momentum:

$$\vec{p}_{i,1} + \vec{p}_{i,2} = \vec{p}_{f,1} + \vec{p}_{f,2}$$

• and cons. of KE:

$$K_{i,1} + K_{i,2} = K_{f,1} + K_{f,2}$$

⇒ solve:

$$\textcircled{1} \quad v_{f,1} = \frac{m_1 - m_2}{m_1 + m_2} v_{i,1} + \frac{2m_2}{m_1 + m_2} v_{i,2}$$

$$\textcircled{2} \quad v_{f,2} = \frac{2m_1}{m_1 + m_2} v_{i,1} + \frac{m_2 - m_1}{m_1 + m_2} v_{i,2}$$

\Rightarrow subtract (2) from (1)

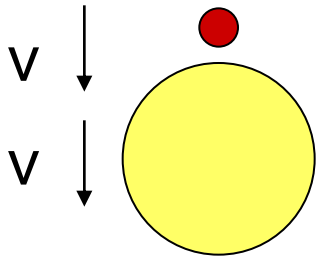
$$\textcircled{3} \quad \underbrace{V_{f,2} - V_{f,1}} = - (V_{i,2} - V_{i,1}) \quad \left. \vphantom{\underbrace{V_{f,2} - V_{f,1}}} \right\} \begin{array}{l} \text{for any 1-D} \\ \text{elastic collision} \end{array}$$

$$\left(\begin{array}{c} \text{speed of} \\ \text{separation} \end{array} \right) = \left(\begin{array}{c} \text{speed of} \\ \text{approach} \end{array} \right) \quad \left. \vphantom{\left(\begin{array}{c} \text{speed of} \\ \text{separation} \end{array} \right)} \right\} \begin{array}{l} \text{same relative} \\ \text{speed before} \\ \text{and after collision} \end{array}$$

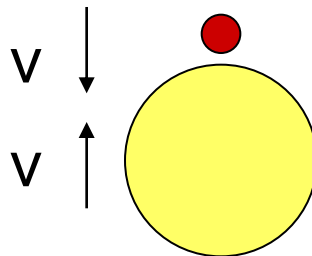
\Rightarrow use equ. (3) + cons. of momentum
to solve elastic collision problems!

Using collisions with large masses to increase speed:

Just before
basketball
hits ground:



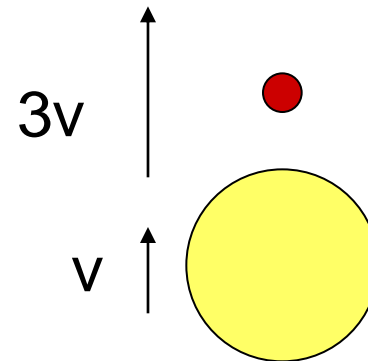
Just after
basketball hits
ground and
before collision
with tennis ball:



**speed of
approach**

$$v_{\text{app}} = v - (-v) = 2v$$

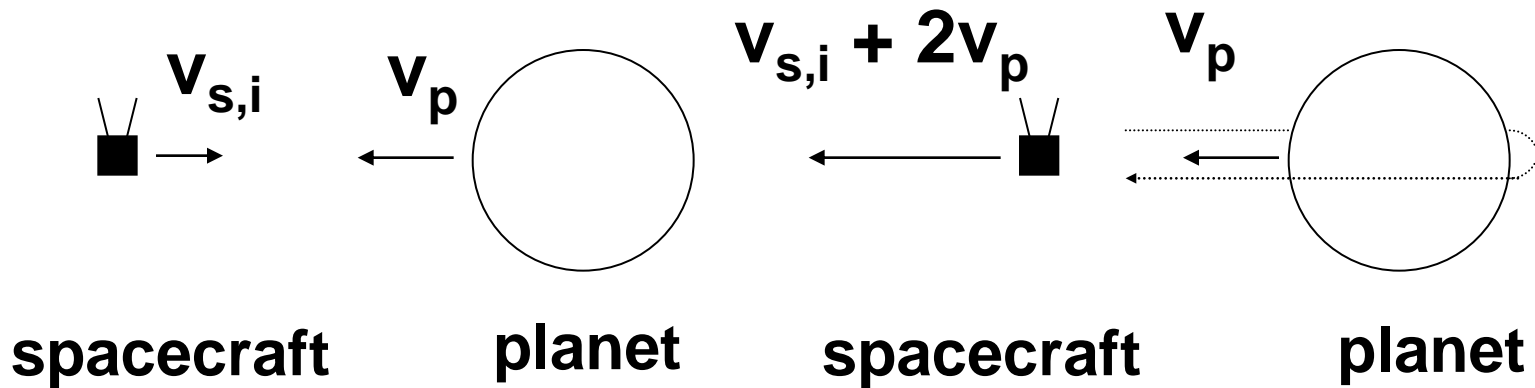
Just after collision
between basket-
ball and tennis
ball:



**speed of
separation**

$$v_{\text{sep}} = 3v - v = 2v$$

Gravitational "Slingshot" Effect:



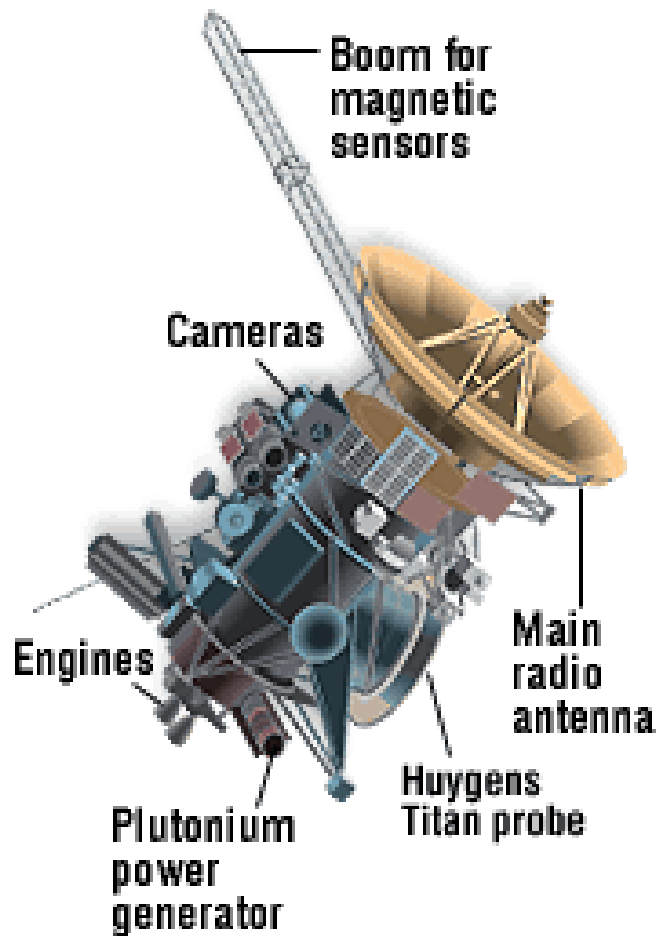
speed of approach

$$v_{app} = |v_{s,i}| + |v_p|$$

speed of separation

$$\begin{aligned} v_{sep} &= v_{s,f} - v_p \\ &= v_{app} = v_{s,i} + v_p \\ \Rightarrow v_{s,f} &= v_{s,i} + 2v_p \end{aligned}$$

Cassini Mission to Saturn:



Four "Slingshot" Gravity Assists:

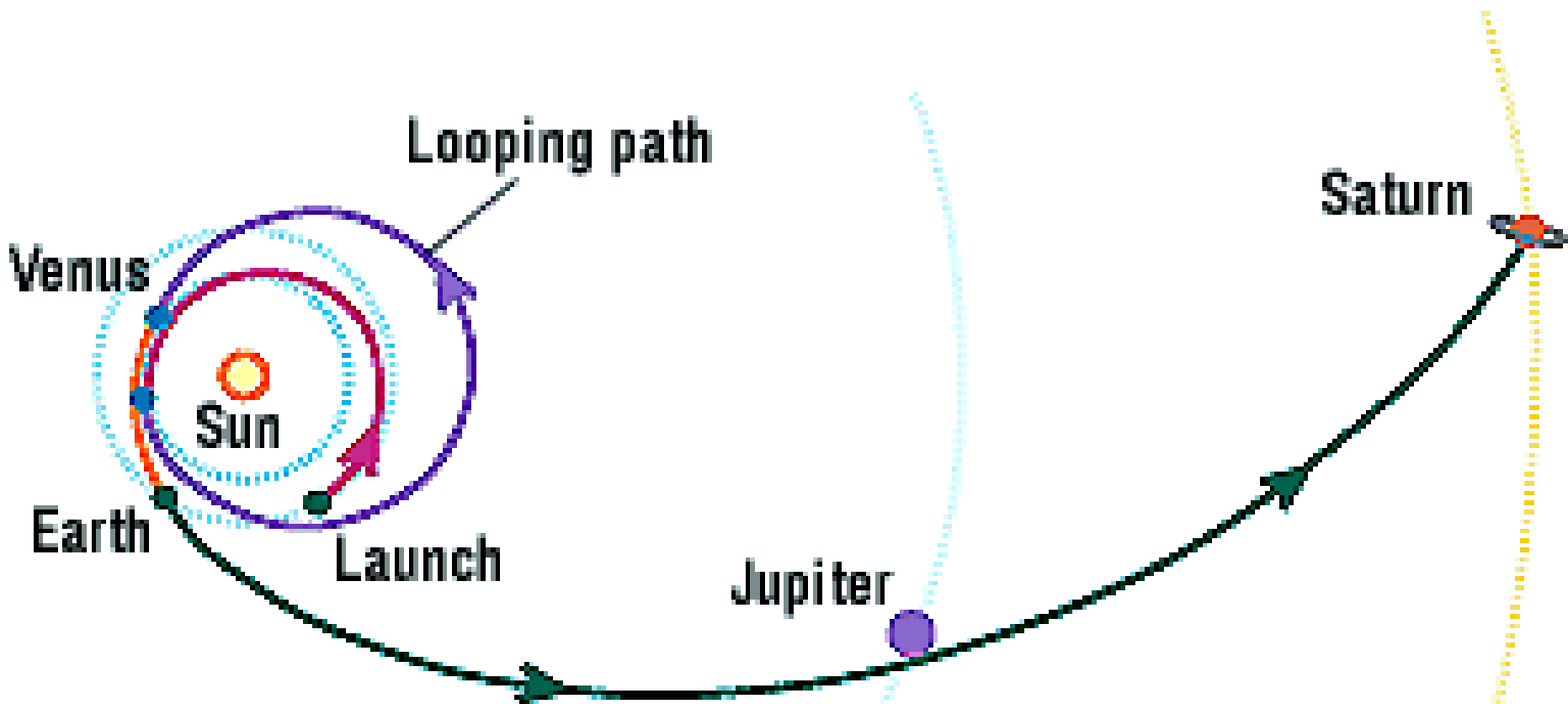
Venus: June 1998

Venus: April 1999

Earth: August 1999

Jupiter: December 2000

Arrive at Saturn: July 2004



A moving object (A) strikes a stationary object (B).

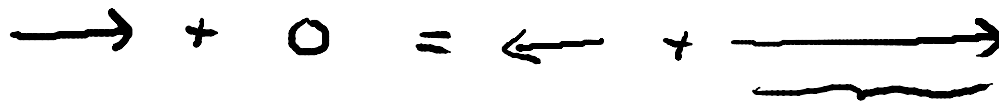


Is it possible for B to end up with more momentum than A had before the collision?

\Rightarrow cons. of total momentum $\vec{P}_{total} \Leftarrow$ vector!

$$\vec{P}_{i,A} + \vec{P}_{i,B} = \vec{P}_{f,A} + \vec{P}_{f,B}$$

| | |
|----|-----|
| A. | Yes |
| B. | No |

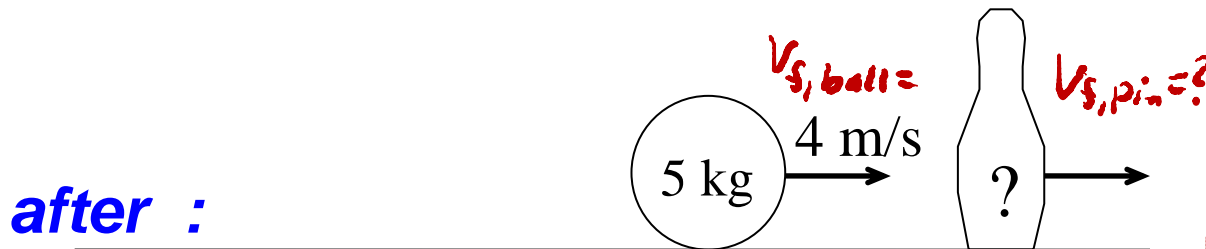
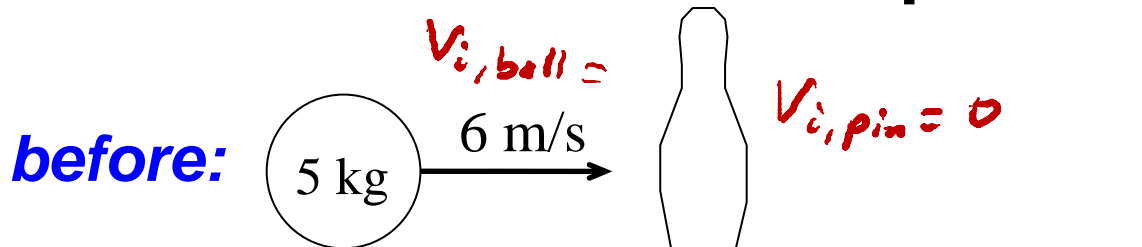


$$|P_{f,B}| > |P_{i,A}| \text{ if } m_B > m_A$$

$$v_{f,B} = \frac{2m_A}{m_A + m_B} v_{i,A} \Rightarrow \underbrace{P_{f,B}} = m_B v_{f,B} = \underbrace{\frac{2m_B}{m_A + m_B}}_{> 1 \text{ if } m_B > m_A} \underbrace{m_A v_{i,A}}_{P_{i,A}}$$

A 5 kg bowling ball collides elastically with a stationary pin of unknown mass.

What is the **final speed** of the pin?



1-D elastic collision: \rightarrow speed of app. = speed of separation

$$6 \text{ m/s} = 10 \text{ m/s} - 4 \text{ m/s}$$

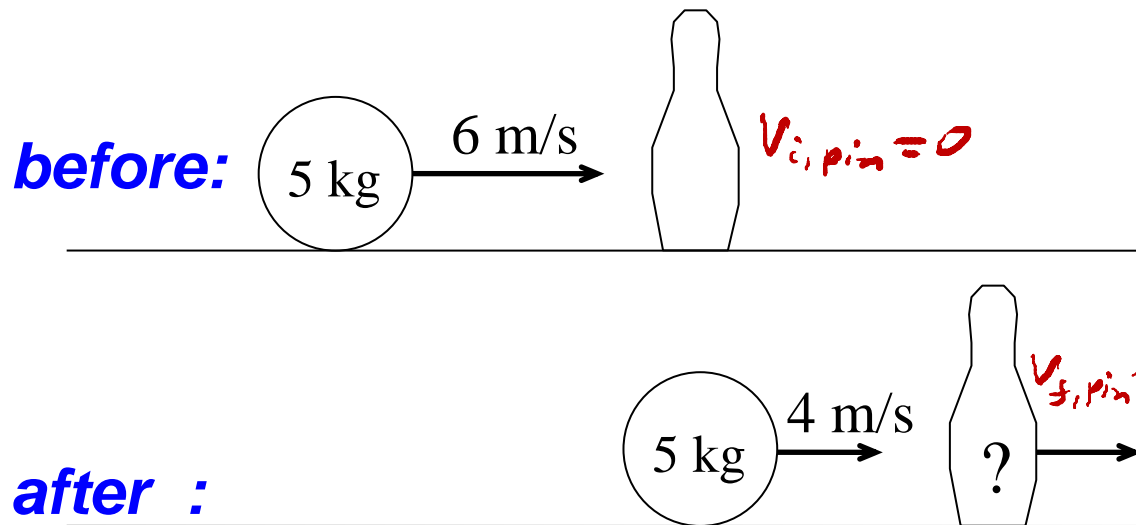
$$v_{s,pin} - v_{s,ball}$$

$v_{pin,final} = ?$

- A. 2 m/s
- B. 4 m/s
- C. 6 m/s
- D. 10 m/s**
- E. not sure

A 5 kg bowling ball collides *elastically* with a stationary pin of unknown mass.

What is the **mass** of the pin?



$m_{\text{pin}} = ?$

- A.** 1 kg
- B.** 5 kg
- C.** 10 kg
- D.** not sure

\Rightarrow use cons. of momentum:

$$m_b v_{i,b} + m_p v_{i,p} = m_b v_{f,b} + m_p v_{f,p}$$

$$\Rightarrow \underbrace{5 \text{ kg} \cdot 6 \text{ m/s}}_{30 \text{ kg m/s}} + 0 = \underbrace{5 \text{ kg} \cdot 4 \text{ m/s}}_{20 \text{ kg m/s}} + \underbrace{m_p \cdot 10 \text{ m/s}}_{10 \text{ kg m/s}} \Rightarrow m_p = 1 \text{ kg}$$