

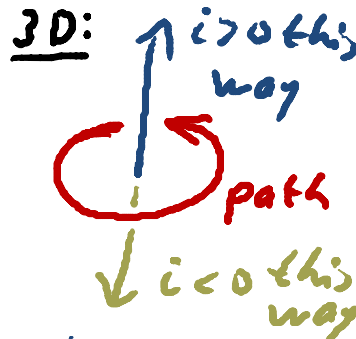
Recap

Lecture 19

- Ampere's Law: relates current to magnetic field it produces

$$\oint_{\text{closed path}} \vec{B} \cdot d\vec{s} = \oint B \cos \theta ds = \oint B_{\parallel \text{to path}} ds = \mu_0 i_{\text{enc, net}}$$

integration path can have any shape, but must be closed.

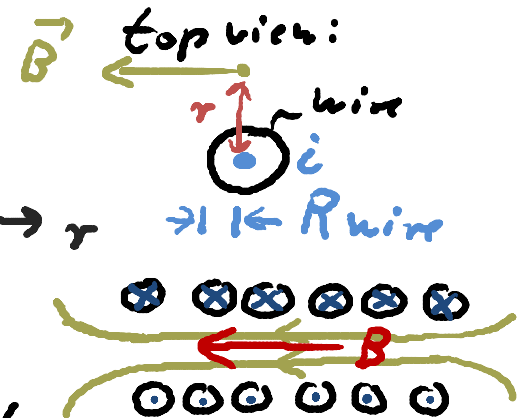
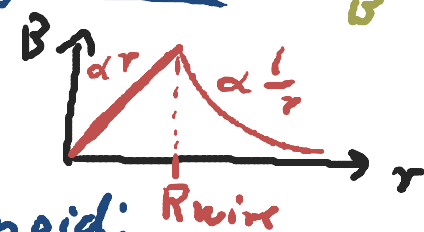


- watch out for correct sign of current (use right-hand rule)
- Only include currents completely enclosed by the integration path

- Magnetic field by a long, straight wire:

$$|B| = \frac{\mu_0 i}{2\pi R_{\text{wire}}} \quad \text{for } r < R_{\text{wire}}$$

$$|B| = \mu_0 / 2\pi \cdot \frac{i}{r} \quad \text{for } r > R_{\text{wire}}$$

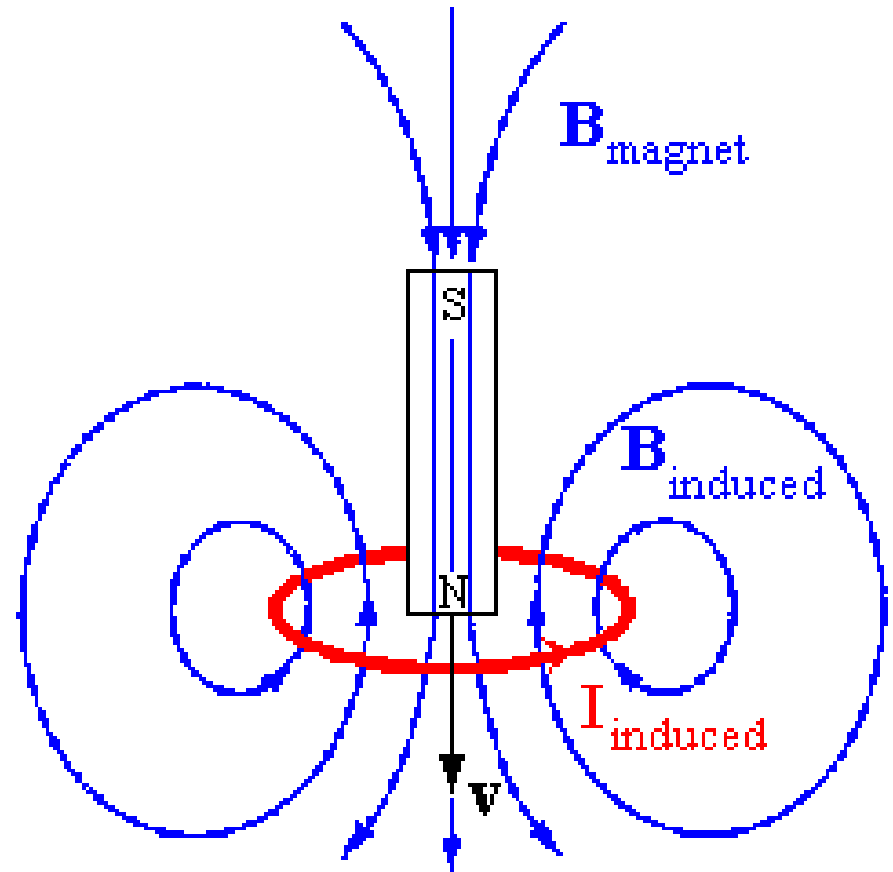


- Magnetic field by a long solenoid:

$$B_{\text{inside}} = \mu_0 i n \leftarrow n = \# \text{ of turns of solenoid per length}$$

Today:

- Magnetic materials
- Change in magnetic flux and Faraday's law of induction
- Lenz's law



Magnetic Materials

- **Ferromagnetic:**

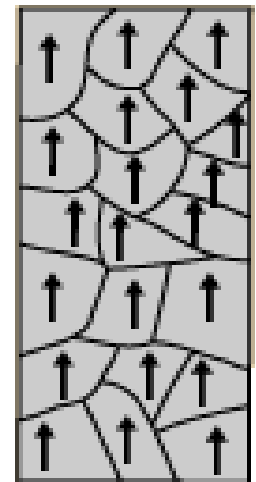
- Examples: Iron, nickel...
- Divided into regions (“**domains**”) in which atomic magnetic dipoles line up
- If placed in an external magnetic field: dipoles of **domains line up in direction of magnetic field**

-> material develops a strong magnetic dipole moment in direction of the applied external magnetic field

- The dipole moment alignment (“magnetization”) **partially persists** when the external field is removed -> permanent magnet



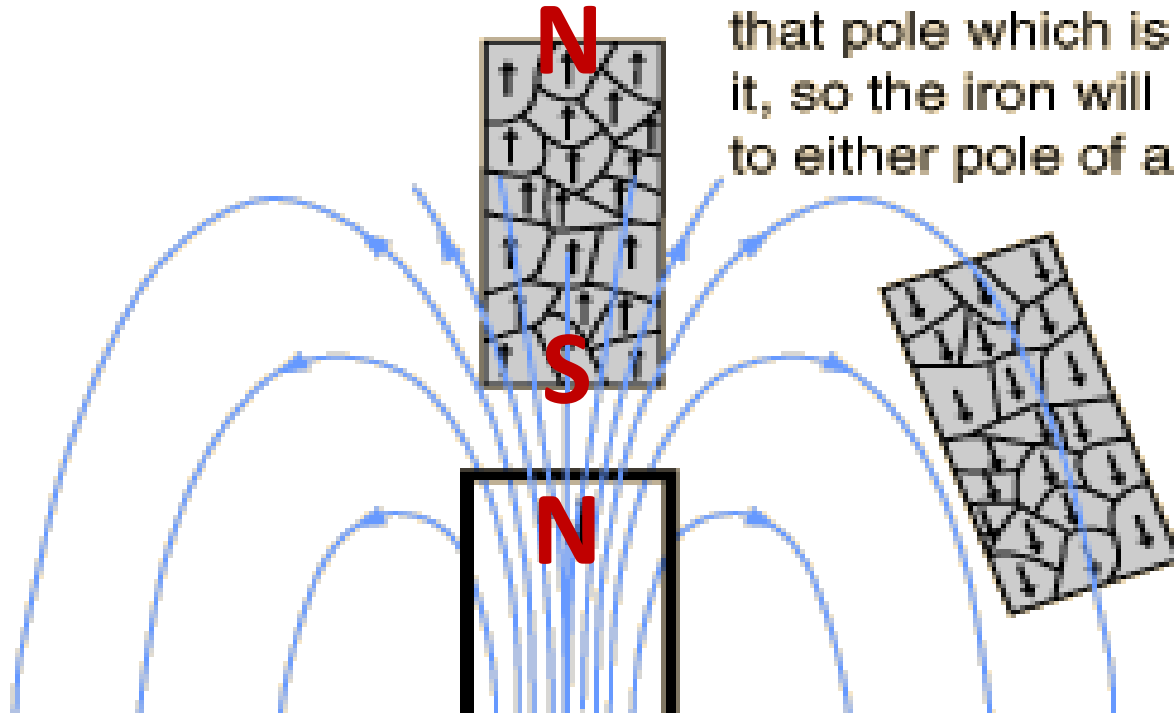
In bulk material the domains usually cancel, leaving the material unmagnetized.



↑↑↑↑↑
Externally applied magnetic field.

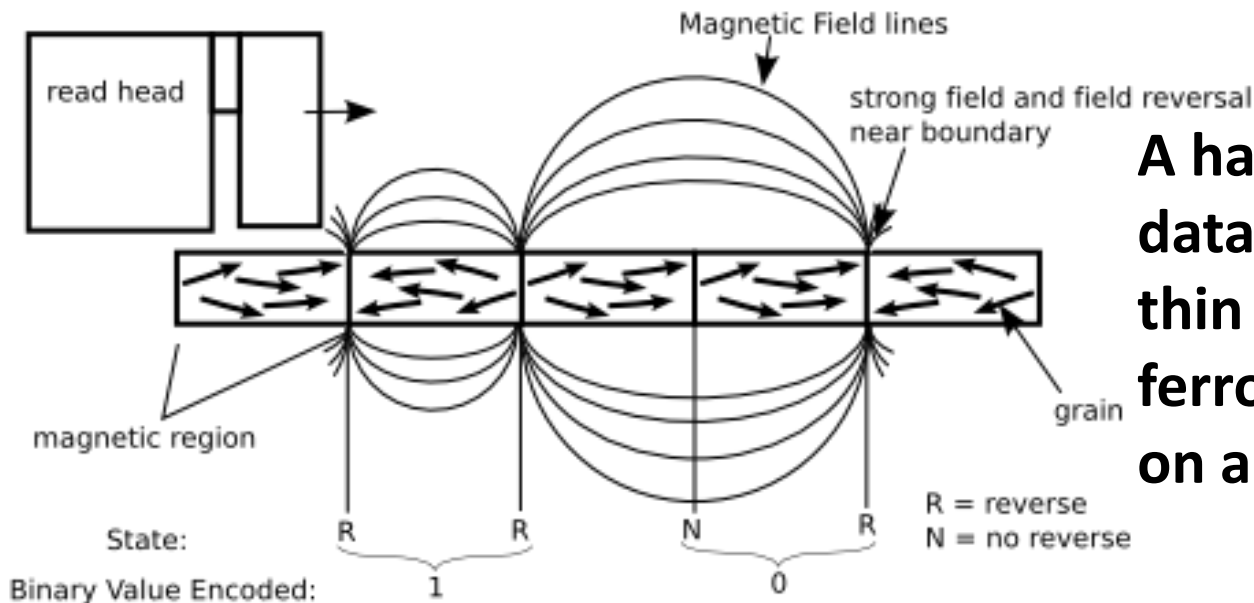
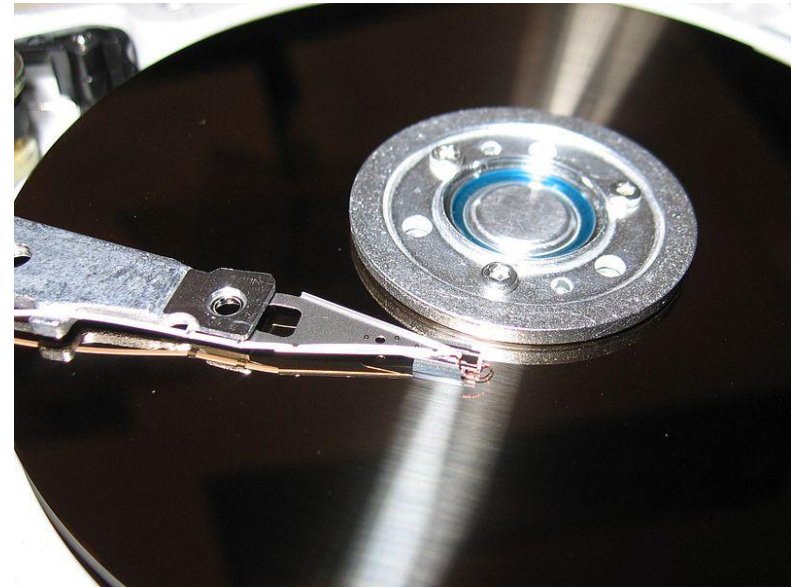
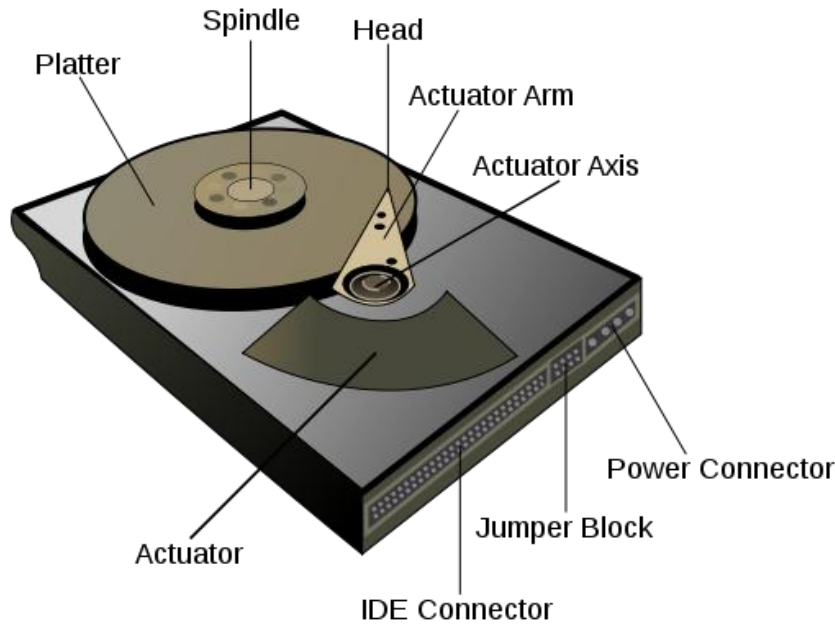
Iron will become magnetized in the direction of any applied magnetic field. This magnetization will produce a magnetic pole in the iron opposite to

that pole which is nearest to it, so the iron will be attracted to either pole of a magnet.



That's why a magnet sticks to a steel refrigerator door...

Example: Hard disk drive



A hard disk drive records data by magnetizing a thin film of ferromagnetic material on a disk.

- **Diamagnetic:**

- Atoms have **no permanent dipole moments**, but weak magnetic dipole moments are produced in the atoms when placed in an external magnetic field
 - >Create a very weak **magnetic dipole field in opposition to an externally applied magnetic field**
- Dipole moments and **net field disappear** when external magnetic field is removed

- **Paramagnetic:**

- Atoms have **permanent dipole moments**, but are randomly oriented
- When placed in an external magnetic field, dipoles partially align in direction of the field
 - >Create a **net magnetic dipole field in direction of the externally applied magnetic field**
- Alignment and **net field disappear** when external magnetic field is removed

Example: Levitation of a Frog on a strong Magnetic Field

- A live frog levitates inside a 32 mm diameter vertical bore of a solenoid in a magnetic field of about 16 T.
- Why?
 - Diamagnetism of the frog
 - Magnetic dipole moment of frog opposes B_{ext} -> repulsive force!





Magnetic Induction:

→ so far:

- electric charge moving in a magnetic field \Rightarrow force $\vec{F} = q \vec{v} \times \vec{B}$
- moving electric charge \Rightarrow produces a magnetic field around itself

$$d\vec{B} = \frac{\mu_0}{4\pi} i \frac{d\vec{s}' \times \vec{r}}{r^2}$$

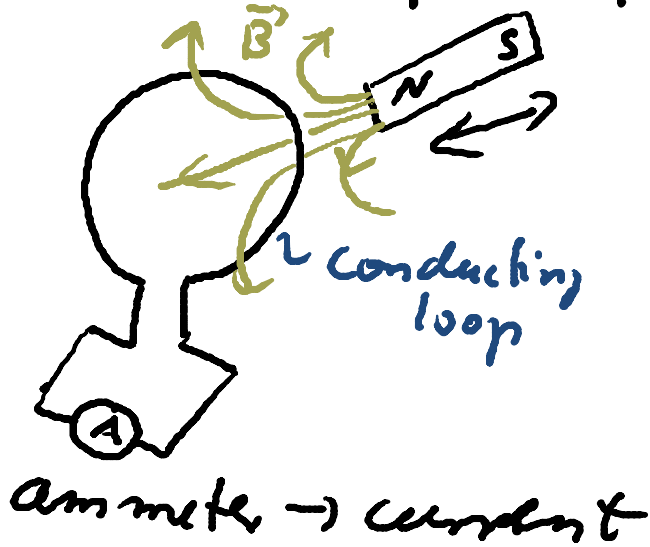
→ now:

changing magnetic field
(magnetic flux Φ_B)
through a conducting
loop

\Rightarrow produces a current
("induced current")
in the conducting loop
 \Leftrightarrow produces/induces an
emf that makes the
current flow \Leftrightarrow
induces an electric field
in the loop

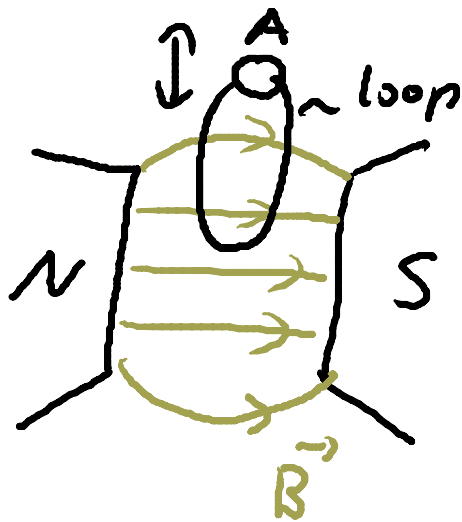
Examples of Magnetic Induction:

I



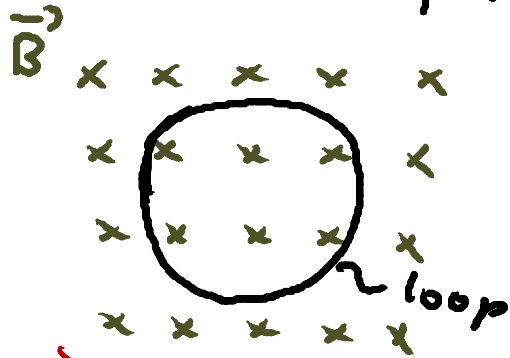
moving magnet
 \Downarrow
change in magnetic flux
going through the loop
 \Downarrow
induces emf / current in the loop

II

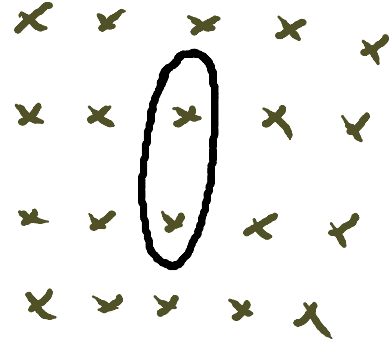


moving coil of wire through
localized magnetic field
 \Downarrow
change in magnetic flux through
the loop
 \Downarrow
induces emf / current in the loop

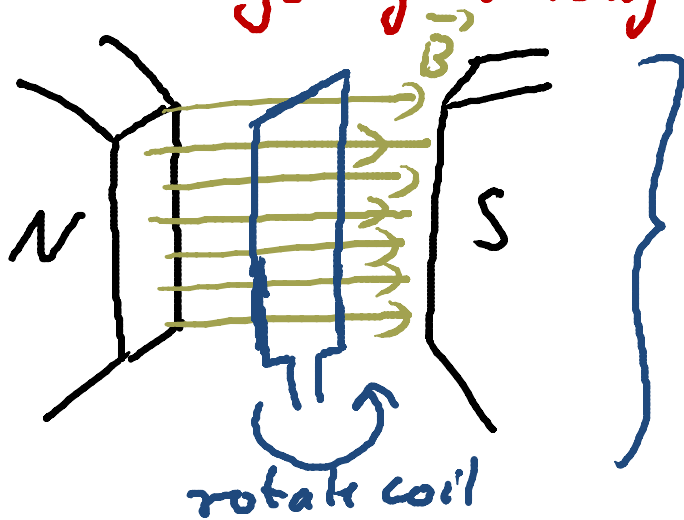
III changing flux through loop
 by changing area or orientation
 of the loop in B-Field \Rightarrow induces emf/
 current in the loop



\longleftrightarrow
 expand and
 flatten loop

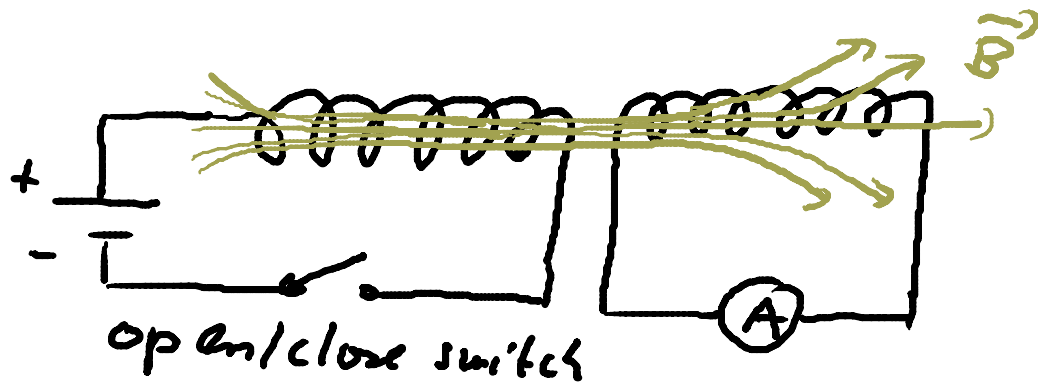


Notice: changes "number of field lines" or magnetic flux Φ_B
 going through the conducting loop



rotating coil
 \Downarrow
 magnetic flux through coil changes
 with time
 \Downarrow
 induces emf / current in coil
 \Rightarrow electric generator!

IV



\Rightarrow changing magnetic field \vec{B}

\Rightarrow changing magnetic flux through coil on the right side

\Rightarrow emf / current is induced in coil on the right side

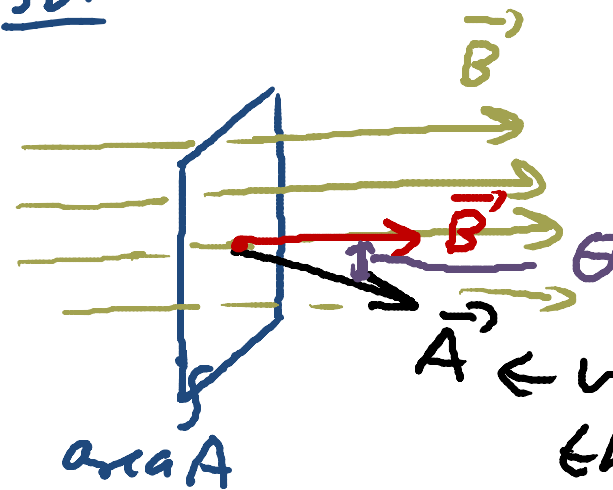
Notice:

- emf / current is only induced if magnetic flux Φ_B through the loops is changing with time!
 \Rightarrow need $d\Phi_B/dt \neq 0$
- Direction of current is different for $d\Phi/dt > 0$ (increase in flux with time) and $d\Phi_B/dt < 0$ (decrease in flux with time)

Quantitative Treatment: Define magnetic flux Φ_B
 (magnetic flux through area A) \propto (number of field lines going through area A)

\rightarrow for uniform magnetic field and flat area:

3D:



$$\boxed{\Phi_B = \vec{B} \cdot \vec{A} = BA \cos \theta}$$

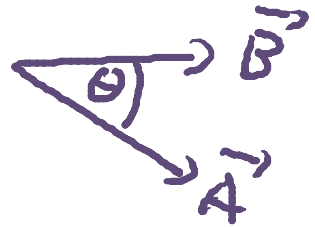
} can be > 0
or < 0

$$\Phi_B = B_{\parallel \text{ to } \vec{A}} A$$

(i.e. \perp to
area A)

$\vec{A} \leftarrow$ vector of magnitude A ,
that is perpendicular to
area A

\uparrow
angle between
 \vec{B} and \vec{A}



Units: $[\Phi_B] = T m^2 = 1 \text{ weber} = 1 \text{ WB}$

→ for more general case:

non-flat surface and/or non-uniform field:

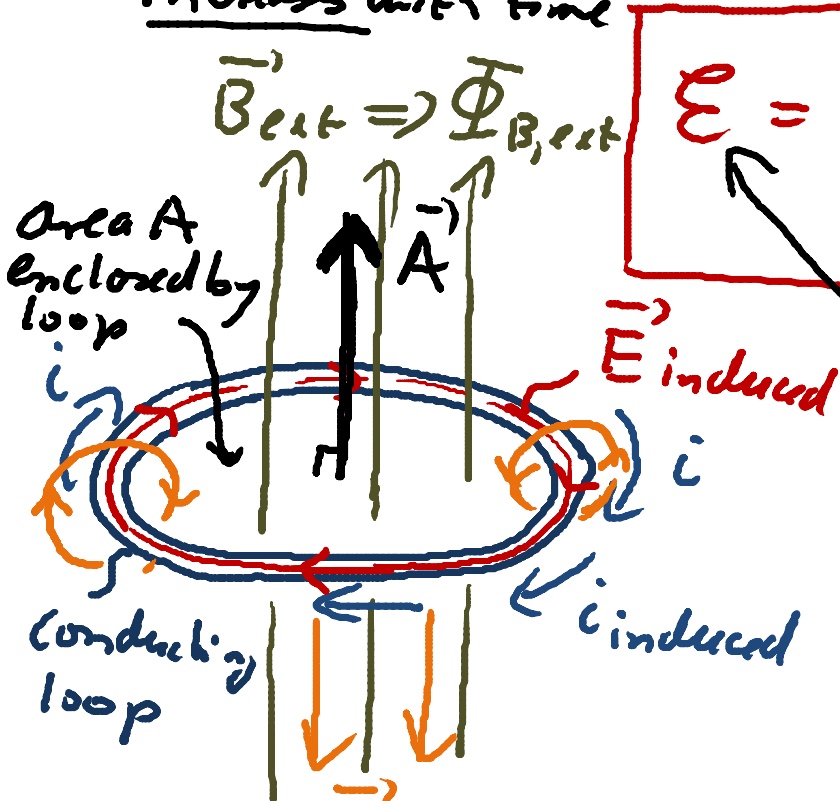
break area into small sections with $\vec{B} \approx \text{const}$
and sum up / integrate over all contributions
to the total flux:

$$\Phi_B = \sum_i \vec{B}_i \cdot \Delta \vec{A}_i = \int_{\text{area}} \vec{B} \cdot d\vec{A}$$

Faraday's Law of Induction:

(emf induced in a conducting loop) = - (rate at which the external magnetic flux $\Phi_{B,ext}$ through that loop changes with time)

3D: Assume ext \vec{B}_{ext} increases with time



$$\mathcal{E} = - \frac{d\Phi_{B,ext}}{dt}$$

$[\mathcal{E}] = \text{volts}$

\mathcal{E} can be positive or negative \Rightarrow sign tells you which way current flows in the loop:



\Rightarrow see Lenz's Law

for coil with N turns:

$$\mathcal{E} = -N \frac{d\Phi_B}{dt}$$

$\vec{B}_{induced}$ } produced by $i_{induced}$