

Sub Lecture: 2 body problem

↑
vs. "The" 2 body problem

TODAY: 2 BODY STUFF — no homework!

FRI: Mo' LECTURES, REVIEW SESSION

MON: Prelim!

2-body problem:

2 point masses, $M_1 @ \vec{r}_1$ & $M_2 @ \vec{r}_2$
subject to a conservative force that
depends only on $(\vec{r}_1 - \vec{r}_2)$

⇒ completely solvable in Lagrangian formalism

$$L = \frac{1}{2} M_1 \dot{\vec{r}}_1^2 + \frac{1}{2} M_2 \dot{\vec{r}}_2^2 - \underbrace{V(\vec{r}_1 - \vec{r}_2)}$$

↑
GENERAL GR NOW. WILL FOCUS
KEEP ON GRAV + ELECTROSTATIC.

CM motion is trivial in isolated sys (no ext f.)

so use CM as a coord:

$$\vec{R} = \frac{M_1 \vec{r}_1 + M_2 \vec{r}_2}{M_1 + M_2}$$

← 327 STUDENTS:
THIS IS THE
MONOPOLAR MOMENT!

since $V = V(\vec{r}_1 - \vec{r}_2)$

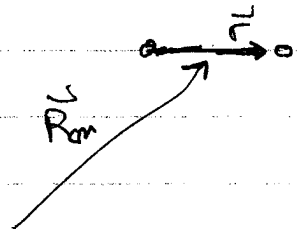
use $\vec{r} = \vec{r}_1 - \vec{r}_2$ as second coord.
[not quite a dipole moment]

BUT for 2 body, (\vec{R}, \vec{r}) A COMPLETE BASIS.

You found :

$$\vec{r}_1 = \vec{R} + \frac{M_2}{M_1 + M_2} \vec{r}$$

$$\vec{r}_2 = \vec{R} - \frac{M_1}{M_1 + M_2} \vec{r}$$



Plug into kinetic energy:

$$T = \frac{1}{2} M_1 \left| \dot{\vec{R}} + \frac{M_2}{M_1 + M_2} \dot{\vec{r}} \right|^2 + \frac{1}{2} M_2 \left| \dot{\vec{R}} - \frac{M_1}{M_1 + M_2} \dot{\vec{r}} \right|^2$$

$$= \frac{1}{2} \underbrace{(M_1 + M_2)}_{\text{TOTAL MASS}} \left| \dot{\vec{R}} \right|^2 + \frac{1}{2} \underbrace{\frac{M_1 M_2^2 + M_2 M_1^2}{(M_1 + M_2)^2}}_{\text{REDUCED MASS}} \left| \dot{\vec{r}} \right|^2$$

no cross term!
of "total charge"

$$\left(\frac{M_1 M_2}{M_1 + M_2} \right) \equiv \mu$$

REDUCED MASS

$$L = \frac{1}{2}(M_1 + M_2) |\dot{\vec{R}}|^2 + \frac{1}{2}\mu |\dot{\vec{r}}|^2 - V(r)$$

↑ indep of \vec{R}

$$\Rightarrow \vec{P}_R = \frac{\partial L}{\partial \dot{\vec{R}}} = (M_1 + M_2) \dot{\vec{R}} \quad \text{CONSERVED}$$

$\underbrace{\hspace{10em}}_{\text{TOTAL MOMENTUM}}$

is it obvious? yes, eg intermolecular forces which keeps things together as I throw them in space.

NO EXTERNAL FORCES \leftrightarrow no $V(\vec{R})$

RELATIVE POSITION

$$\frac{\partial L}{\partial \dot{\vec{r}}} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\vec{r}}} \right)$$

$$\left[-V'(r) \frac{\partial r}{\partial \vec{r}} = \mu \ddot{\vec{r}} \right] \Rightarrow \mu \ddot{\vec{r}} = -V'(r) \hat{r}$$

in the \hat{r} direction.

↑ $V'(\dots)$ derivative wrt arg.

↑ we used: V is scalar w/ vec-arg, can only depend on $r^2 = |\vec{r}|^2$

one body problem
for point mass (μ) subj. to central force $\vec{F} = -V'(r) \hat{r}$

\vec{r} & $\vec{v} = \dot{\vec{r}}$ define a plane w/ normal vec $\vec{v} \times \vec{r}$.

note: $\frac{d}{dt} (\dot{\vec{r}} \times \vec{r}) = \ddot{\vec{r}} \times \vec{r} + \dot{\vec{r}} \times \dot{\vec{r}} = 0$

BUT $\ddot{\vec{r}} \sim \hat{r}$ FROM BEFORE?

thus normal vec to plane is constant
 \Rightarrow plane is constant.

w/o log: let $\vec{r} \in xy$ plane

\checkmark ignore from now on: $L = L_{cm} + L_{rel}$, SEPARABLE

$$L = [KE \text{ of cm}] + \frac{1}{2} \mu |\dot{\vec{r}}|^2 - V(|\vec{r}|)$$

Go to polar: $x = r \cos \theta$
 $y = r \sin \theta$

$$L = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) - V(r)$$

\uparrow indep of θ : $L_z = l = \frac{\partial L}{\partial \dot{\theta}} = \mu r^2 \dot{\theta} = \text{const.}$
angular momentum

so: original problem: 2×3 DoF

now: 1 dof, dep on V .

$$\frac{\partial L}{\partial r} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right)$$

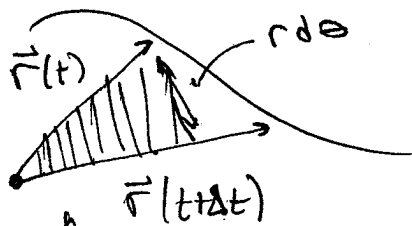
$$\Rightarrow \mu r \dot{\theta}^2 - V'(r) = \mu \ddot{r}$$

$$\frac{l^2}{\mu r^3}$$

$$\Rightarrow \mu \ddot{r} = \frac{l^2}{\mu r^3} - V'(r)$$

We will study this in detail
 → elliptical shape of orbits, etc.

Kepler : $l = \text{const}$



$$dA = \frac{1}{2} r^2 d\theta \Rightarrow \frac{dA}{dt} = \frac{1}{2} r^2 \frac{d\theta}{dt} = \frac{1}{2} r^2 \dot{\theta} = \frac{l}{2\mu} = \text{const.}$$

did this dep on GRAV? μ -square?

Conserved quantities like l are called
FIRST INTEGRALS (w/c EOM ARE 2ND O DIFF EQ
 & CONS QUANTITIES ARE 1ST O)

The other obvious one is the Hamiltonian / E

$$E = \frac{1}{2}\mu(\dot{r}^2 + r^2\dot{\theta}^2) + V(r) = 2T - L$$

$$= \frac{1}{2}\mu\dot{r}^2 + \underbrace{\frac{1}{2}\frac{l^2}{\mu r^2}}_{V_{\text{eff}}} + V(r) \quad \begin{matrix} \uparrow \\ \text{orbital} \end{matrix}$$

$$\frac{dr}{dt} = \pm \sqrt{\frac{2}{\mu}(E - V) - \frac{l^2}{\mu^2 r^2}}$$

↑ more gen: $E = \frac{1}{2}\dot{\theta}^2 + V \rightarrow \dot{\theta} = \sqrt{2(E - V(\theta))}$

$$dt = \frac{d\theta}{\pm \sqrt{2(E - V(\theta))}}$$

instead, can also do

$$d\theta = \frac{d\theta}{dt} \frac{dt}{dr} dr = \dot{\theta}/\dot{r} dr \quad \text{w/} \quad \dot{\theta} = l/\mu r^2$$

$$\theta(r) = \int \frac{l(l/r^2) dr}{\sqrt{2\mu(E - V - l^2/(2\mu r^2))}}$$

$$MR_{om} = m_i r_i$$

$$R_i = r_i - r_{i+1}$$

$$M r_i = MR_{om} - \sum_{k=i}^N M_k R_k + \sum_{k \neq i} M_k R_k + \sum_{k=i+1}^N M_k R_k$$

no x terms.

g:	R_{om}	R_1	R_2	R_3	R_4
r_1	M_1	$-M_1$			
r_2	M_2	$+M_1$	$-M_1, M_2$		
r_3	M_3		$+M_1, +M_2$	$+M_4 + M_5$	
r_4	M_4			$-M_4 - M_5$	$+M_5$
r_5	M_5				$-M_5$

$$\sum_{k \neq a} M_b \left(\sum_{k \neq a} -M_k \right)$$

$$M_a \left(\sum_{k \neq a} M_k \right)$$

$$\sum_{c \neq a} M_c \left(\sum_{k \neq a} M_k \right)$$

$$\sum_{c \neq a} M_c \sum_{k \neq a} M_k$$